

# **Advanced Microeconomic Theory**

## **Chapter 10: Contract Theory**

# Outline

- Moral Hazard
- Moral Hazard with a Continuum of Effort Levels—The First-Order Approach
- Moral Hazard with Multiple Signals
- Adverse Selection—The “Lemons” Problem
- Adverse Selection—The Principal-Agent Problem
- Application of Adverse Selection—Regulation

# Moral Hazard

# Moral Hazard

- **Moral hazard**: settings in which an agent does not observe the actions of the other individual(s).
  - Also referred to as “hidden action”
- Example:
  - A manager in a firm cannot observe the effort of employees in the firm even if the manager is perfectly informed about the worker’s ability or productivity.
  - The worker might have incentives to *slack* from exerting a costly effort, thus giving rise to moral hazard problems.

# Moral Hazard

- The manager can offer contracts that provide incentives to the worker to work hard
  - Paying a higher salary (bonus) if the worker's output is high but a low salary otherwise.
- Providing incentives to work hard is costly for the manager
- The manager only induces a high effort if the firm's expected profits are higher than those of inducing a low effort

# Moral Hazard

- Consider a principal with benefit function

$$B(\pi - w)$$

where  $\pi$  is the profit that arises from the agent's effort and  $w$  is the salary that the principal pays to the agent.

- The benefit function satisfies  $B' \geq 0$  and  $B'' \leq 0$ .
- The agent's (quasi-linear) utility function is

$$U(w, e) = u(w) - g(e)$$

where  $u(w)$  is utility from the agent's salary, for  $u' > 0$  and  $u'' \leq 0$ , and  $g(e)$  is the agent's disutility from effort ( $e$ ), for  $g' > 0$  and  $g'' \geq 0$ .

# Moral Hazard

- The agent's effort level  $e$  affects the probability that a certain profit occurs.
- For a given effort  $e$ , the conditional probability that a profit  $\pi = \pi_i$  is

$$f(\pi_i|e) = \text{Prob}\{\pi = \pi_i|e\} \geq 0$$

where  $i = \{1, 2, \dots, N\}$  is the profits that can emerge for a given effort  $e$ .

- Hence a high profit could arise even if the worker slacks
  - That is, a given profit level  $\pi = \pi_i$  can arise from every effort level

# Symmetric Information

- The principal **can observe** the agent's effort level  $e$ .
- The principal's maximization problem is

$$\max_{\{e, w(\pi_i)\}_{i=1}^N} \sum_{i=1}^N f(\pi_i | e) \cdot B(\pi_i - w(\pi_i))$$

$$\text{s.t. } \sum_{i=1}^N f(\pi_i | e) u(w(\pi_i)) - g(e) \geq \bar{u}$$

- The principal seeks to maximize expected profits, subject to the agent participating in the contract.
  - The constraint guarantees the agent's voluntary participation in the contract.
  - Hence it is referred to as the participation constraint (PC) or the “individual rationality” condition.
- The constraint must be binding (holding with equality).

# Symmetric Information

- The Lagrangian that solves the maximization problem is

$$\mathcal{L} = \sum_{i=1}^N f(\pi_i | e) \cdot B(\pi_i - w(\pi_i)) \\ + \lambda \left[ \sum_{i=1}^N f(\pi_i | e) u(w(\pi_i)) - g(e) - \bar{u} \right]$$

- Take FOC with respect to  $w$  to obtain

$$f(\pi_i | e) \cdot B'(\pi_i - w(\pi_i)) \cdot (-1) \\ + \lambda f(\pi_i | e) u'(w(\pi_i)) = 0$$

where  $B'$  and  $u'$  are the derivative of  $B(\cdot)$  and  $u(\cdot)$  with respect to  $w$ , respectively.

# Symmetric Information

- Rearranging

$$\lambda u'(w(\pi_i)) = B'(\pi_i - w(\pi_i))$$

- Solving for  $\lambda$

$$\lambda = \frac{B'(\pi_i - w(\pi_i))}{u'(w(\pi_i))} \tag{1}$$

which is positive since  $B'(\cdot) > 0$  and  $u'(\cdot) > 0$ .

- $\lambda > 0$  entails that the agent's participation constraint must bind (i.e., hold with equality)

$$\sum_{i=1}^N f(\pi_i | e) u(w(\pi_i)) - g(e) = \bar{u}$$

# Symmetric Information

- Example 1:
  - Consider a risk-neutral principal hiring a risk-averse agent with utility function  $u(w) = \sqrt{w}$ , disutility of effort  $g(e) = e$ , and reservation utility  $\bar{u} = 9$ .
  - There are two effort levels  $e_H = 5$  and  $e_L = 0$ .
  - When  $e_H = 5$ , the principal's sales are \$0 with probability 0.1, \$100 with probability 0.3, and \$400 with probability 0.6.
  - When  $e_L = 0$ , the principal's sales are \$0 with probability 0.6, \$100 with probability 0.3, and \$400 with probability 0.1.
  - In the case of  $e_H = 5$ , the expected profit is \$270, while in the case of  $e_L = 0$ , the expected profit is \$70.

# Symmetric Information

- Example 1: (con't)
  - When effort is observable, the principal can induce an effort  $e_H = 5$  by paying a wage  $w_e^*$  that solves
$$u(w_e^*) = \bar{u} + g(e)$$
$$\sqrt{w_e^*} = 9 + 5$$
$$w_e^* = 14^2 = 196$$
  - Similarly, the principal can induce a low effort  $e_L = 0$  by offering a wage
$$\sqrt{w_e^*} = 9 + 0$$
$$w_e^* = 9^2 = 81$$

# Symmetric Information

- Example 1: (con't)
  - Given these salaries, the profits that the principal obtains are
$$\$270 - \$196 = \$74 \text{ from } e_H = 5$$
$$\$70 - \$81 = -\$11 \text{ from } e_L = 0$$
  - Thus the principal prefers to induce  $e_H$  when effort is observable.

# Risk Attitudes

- Continuing with the moral hazard setting under symmetric information, let us now consider the role of **risk aversion**.
- Three cases:
  1. The principal is risk-neutral but the agent is risk-averse
  2. The principal is risk-averse but the agent is risk-neutral
  3. Both the principal and the agent are risk-averse

# Risk Attitudes: Case 1

- The principal is risk-neutral but the agent is risk-averse.
- The principal's benefit function is

$$B(\pi_i - w(\pi_i)) = \pi_i - w(\pi_i)$$

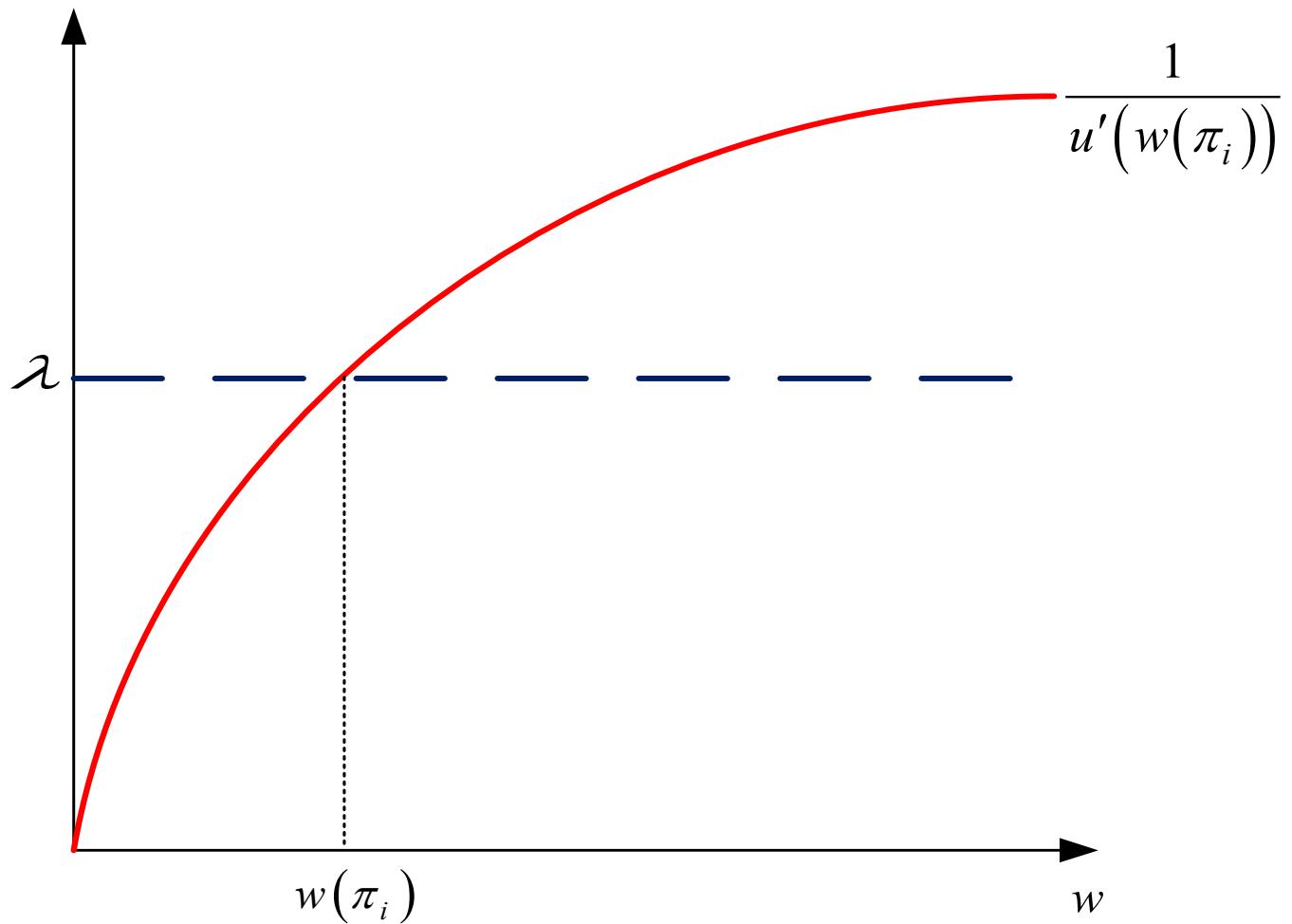
- Hence,

$$B'(\pi_i - w(\pi_i)) = 1$$

- In this context, FOC in expression (1) becomes

$$\lambda = \frac{1}{u'(w(\pi_i))} \text{ for all } \pi_i \tag{2}$$

# Risk Attitudes: Case 1



# Risk Attitudes: Case 1

- FOC in (2) entails that the principal pays a **fixed wage** level for all profit realizations.
- For any  $\pi_i \neq \pi_j$ ,

$$\lambda = \frac{1}{u'(w(\pi_i))} = \frac{1}{u'(w(\pi_j))}$$

$$u'(w(\pi_i)) = u'(w(\pi_j))$$

$$w(\pi_i) = w(\pi_j) \text{ given } u' > 0$$

- This is a **standard risk-sharing result**
  - The risk-neutral principal offers a contract to the risk-averse agent that guarantees the latter a fixed salary of  $w_e^*$  regardless of the specific profit realization that emerges.
  - The risk-neutral principal bears all the risk.

# Risk Attitudes: Case 1

- Since the agent's PC binds, we can express it

$$u(w_e^*) - g(e) = \bar{u}$$

- Rearranging the PC expression

$$u(w_e^*) = \bar{u} + g(e)$$

- Applying the inverse

$$w_e^* = u^{-1}(\bar{u} + g(e))$$

- This expression helps to identify the salary that the principal needs to offer in order to induce a specific effort level  $e$  from the agent.

# Risk Attitudes: Case 1

- For two effort levels  $e_L$  and  $e_H$ , the disutility of effort function satisfies

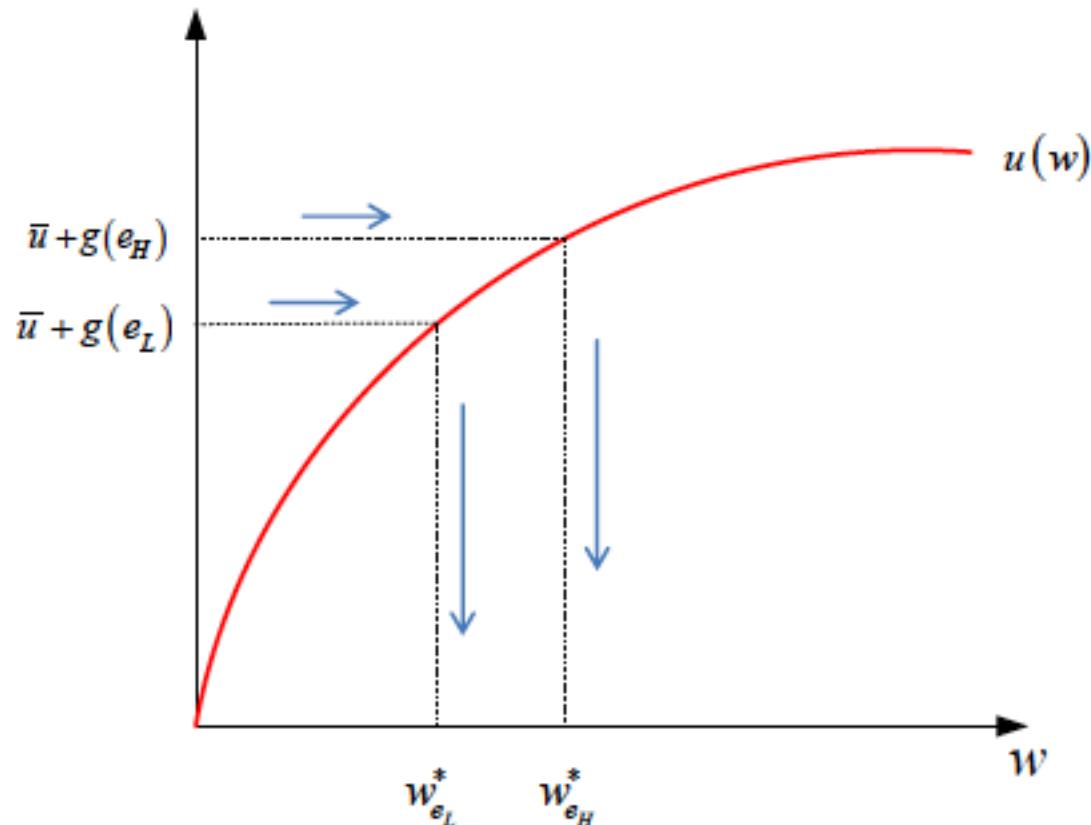
$$g(e_L) < g(e_H)$$

- This entails

$$w_{e_L}^* = u^{-1}(\bar{u} + g(e_L)) < u^{-1}(\bar{u} + g(e_H)) = w_{e_H}^*$$

- In order to induce  $e_H$ , we need to evaluate the utility function at a height of  $\bar{u} + g(e_H)$ .
- Inducing a higher effort implies offering a higher salary.

# Risk Attitudes: Case 1



# Risk Attitudes: Case 1

- We can plug in salary  $w_e^* = u^{-1}(\bar{u} + g(e))$  into the principal's objective function in order to find the effort level that maximizes the principal's expected profits

$$\begin{aligned} & \max_e \sum_{i=1}^N f(\pi_i | e) (\pi_i - w(\pi_i)) \\ &= \max_e \sum_{i=1}^N f(\pi_i | e) \cdot \pi_i - \underbrace{u^{-1}(\bar{u} + g(e))}_{w_e^*} \end{aligned}$$

where  $w_e^*$  does not depend on  $\pi_i$ .

- This helps to reduce the number of choice variables to only the effort level  $e$ .

# Risk Attitudes: Case 1

- Taking FOC with respect to  $e$  yields

$$\sum_{i=1}^N f'(\pi_i|e) \cdot \pi_i - \frac{\partial u^{-1}(\bar{u} + g(e))}{\partial e} g'(e) = 0$$

where  $\frac{\partial u^{-1}(\bar{u} + g(e))}{\partial e}$  can be expressed as  $(u^{-1})'(\bar{u} + g(e))$ .

- By the implicit function theorem,

$$(u^{-1})'(\bar{u} + g(e)) = (u')^{-1}(\bar{u} + g(e))$$

- Hence the above FOC can be rewritten as

$$\sum_{i=1}^N f'(\pi_i|e) \cdot \pi_i = \frac{g'(e)}{u'(\bar{u} + g(e))}$$

# Risk Attitudes: Case 1

- Intuition:
  - Effort  $e$  is increased until the point at which its marginal expected profit (left-hand side) coincides with its certain costs (in the right-hand side), which stems from a larger marginal disutility of effort for the agent (numerator) that needs to be compensated with a more generous salary (denominator).
- See textbook for the second-order condition that guarantees concavity.

# Risk Attitudes: Case 2

- The principal is risk-averse but the agent is risk-neutral.
- The principal's benefit function is  $B(\pi_i - w(\pi_i))$ , with  $B' > 0$  and  $B'' < 0$ .
- The agent's utility function is
$$u(w_i) - g(e) = w_i - g(e)$$
- In this context, FOC in expression **(1)** becomes
$$\lambda = B'(\pi_i - w(\pi_i))$$
where  $u'(w(\pi_i)) = 1$ .

# Risk Attitudes: Case 2

- FOC entails that it is now the principal who obtains a **fixed payoff** for all profit realizations.

- For any  $\pi_i \neq \pi_j$ ,

$$\lambda = B'(\pi_i - w(\pi_i)) = B'(\pi_j - w(\pi_j))$$

$$\pi_i - w(\pi_i) = \pi_j - w(\pi_j) = K \text{ given } B' > 0$$

- That is, the risk-averse principal receives the same payoff regardless of the profit realization  $\pi$ , whereas the risk-neutral agent now bears all the risk.

# Risk Attitudes: Case 2

- The agent's salary is

$$w(\pi_i) = \pi_i - K$$

where  $K$  is found by making the agent indifferent between accepting and rejecting the franchise contract

- Fee  $K$  solves

$$\sum_{i=1}^N f(\pi_i | e) [\pi_i - K] - g(e) = \bar{u}$$

$$K = \sum_{i=1}^N f(\pi_i | e) \pi_i - \bar{u} - g(e)$$

# Risk Attitudes: Case 2

- The principal's expected profit is

$$\begin{aligned} & \sum_{i=1}^N f(\pi_i | e) B(\pi_i - w(\pi_i)) \\ &= \sum_{i=1}^N f(\pi_i | e) B(\pi_i - (\pi_i - K)) \\ &= \sum_{i=1}^N f(\pi_i | e) B(K) = B(K) \end{aligned}$$

- The principal's problem can then be written as

$$\max_e B(K) = B \left( \sum_{i=1}^N f(\pi_i | e) \pi_i - \bar{u} - g(e) \right)$$

# Risk Attitudes: Case 2

- Taking FOC with respect to  $e$  yields

$$B' \left( \sum_{i=1}^N f(\pi_i|e) \pi_i - \bar{u} - g(e) \right) \left( \sum_{i=1}^N f'(\pi_i|e) \pi_i - g'(e) \right) = 0$$

which simplifies to

$$\sum_{i=1}^N f'(\pi_i|e) \pi_i = g'(e)$$

- Intuition:
  - Effort  $e$  is increased until the point where marginal expected profit from having the agent exert more effort (left-hand side) coincides with his marginal disutility (right-hand side).

# Risk Attitudes: Case 2

- The second-order condition is

$$\sum_{i=1}^N f''(\pi_i|e)\pi_i - g''(e) \leq 0$$

where  $g''(e) \geq 0$ .

# Risk Attitudes: Case 3

- Both the principal and the agent are risk-averse.
- Recall the FOCs with respect to  $w$

$$B'(\pi_i - w(\pi_i)) \cdot (-1) + \lambda u'(w(\pi_i)) = 0 \quad (3)$$

$$\lambda = \frac{B'(\pi_i - w(\pi_i))}{u'(w(\pi_i))} \quad (4)$$

- To better understand how the profit-maximizing salary is affected by the profit realization  $\pi_i$ , differentiate (3) with respect to  $\pi_i$

$$\begin{aligned} & -B''(\pi_i - w(\pi_i)) + B''(\pi_i - w(\pi_i))w'(\pi_i) \\ & + \lambda u''(w(\pi_i))w'(\pi_i) = 0 \end{aligned}$$

# Risk Attitudes: Case 3

- Plugging  $\lambda$  from (4) yields

$$\begin{aligned} & -B''(\pi_i - w(\pi_i)) + B''(\pi_i - w(\pi_i))w'(\pi_i) \\ & + \frac{B'(\pi_i - w(\pi_i))}{u'(w(\pi_i))} u''(w(\pi_i))w'(\pi_i) = 0 \end{aligned}$$

- Factoring out  $w'(\pi_i)$  yields

$$\begin{aligned} & B''(\pi_i - w(\pi_i)) \\ & = \left[ B''(\pi_i - w(\pi_i)) + B'(\pi_i - w(\pi_i)) \frac{u''(w(\pi_i))}{u'(w(\pi_i))} \right] w'(\pi_i) \end{aligned}$$

# Risk Attitudes: Case 3

- Solving for  $w'(\pi_i)$  yields

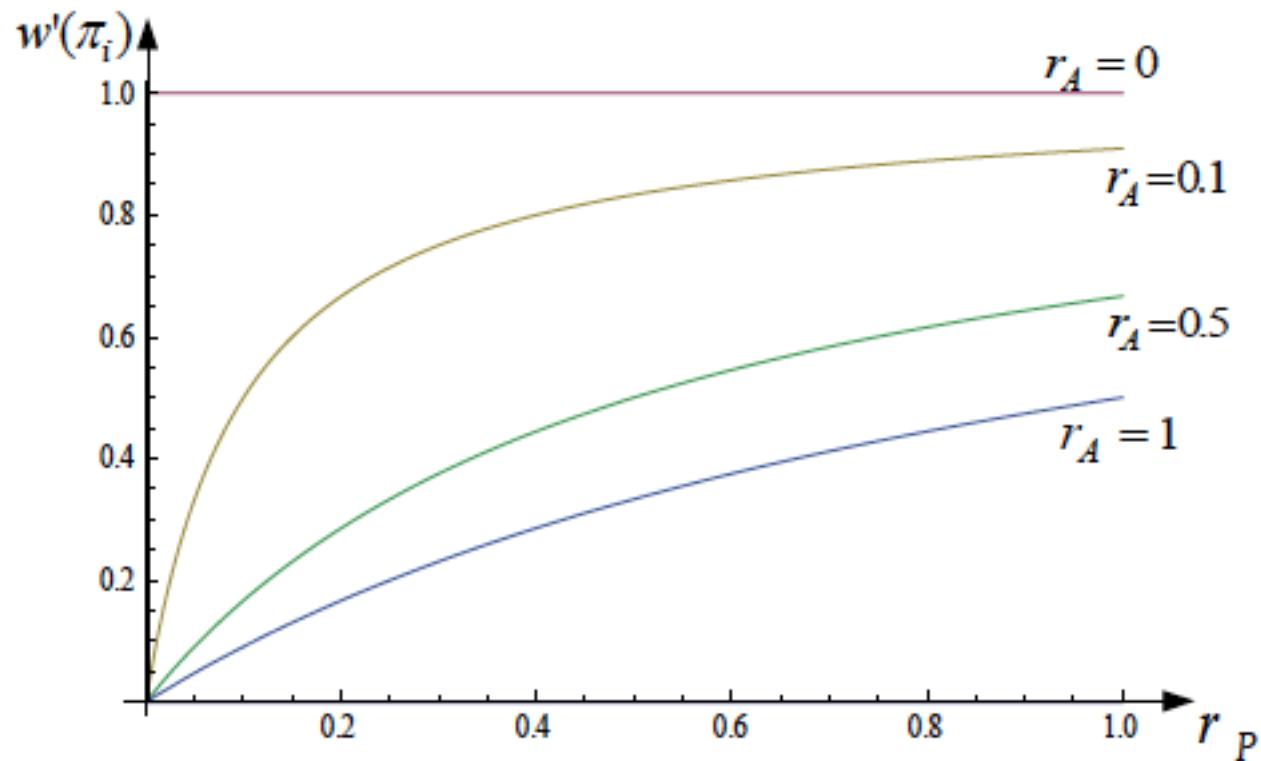
$$w'(\pi_i) = \frac{B''(\pi_i - w(\pi_i))}{B''(\cdot) + \frac{u''(w(\pi_i))}{u'(w(\pi_i))} B'(\cdot)}$$

- Dividing numerator and denominator by  $B'(\cdot)$  yields

$$w'(\pi_i) = \frac{B''(\cdot)/B'(\cdot)}{B''(\cdot)/B'(\cdot) + \frac{u''(\cdot)}{u'(\cdot)}} = \frac{r_P}{r_P + r_A} \tag{5}$$

where  $r_P$  and  $r_A$  denote the the **Arrow–Pratt coefficient of absolute risk aversion** of the principal and the agent, respectively.

# Risk Attitudes: Case 3



# Risk Attitudes: Case 3

- Let us next evaluate the ratio in expression (5) at different values of  $r_P$  and  $r_A$ .
- **Risk-neutral principal:**  $r_P = 0$ 
  - The expression in (5) becomes  $w'(\pi_i) = 0$ .
  - This result holds regardless of the agent's coefficient of risk aversion  $r_A > 0$ .
- This setting coincides with that in Case 1, where the agent receives a fixed wage to insure him against the profit realization  $\pi_i$ , whereas the risk-neutral principal bears all the risk.

# Risk Attitudes: Case 3

- **Risk-neutral agent:**  $r_A = 0$ 
  - The expression in (5) becomes  $w'(\pi_i) = 1$ .
  - This holds regardless of principal's coefficient of risk aversion  $r_P > 0$ .
  - This setting coincides with that in Case 2, where the risk-neutral agent bears all the risk while the principal receives a fixed payment  $K$  that insures the principal against different profit realization  $\pi_i$ .

# Risk Attitudes: Case 3

- **Agent is more risk-averse than principal:**  $r_A > r_P > 0$ 
  - The expression in (5) becomes  $w'(\pi_i) < 1/2$ .
  - It is optimal for the agent's salary  $w'(\pi_i)$  to exhibit small variations in the profit realization  $\pi_i$ .
  - The more risk-averse agent bears less payoff volatility.

# Risk Attitudes: Case 3

- **Principal is more risk-averse than agent:**  $r_P > r_A > 0$ 
  - The expression in (5) becomes  $w'(\pi_i) > 1/2$ .
  - The less risk-averse agent bears more payoff volatility.

# Risk Attitudes: Case 3

- **Same degree of risk aversion:**  $r_A = r_P = r > 0$ 
  - The expression in (5) becomes  $w'(\pi_i) = 1/2$ .
  - Both the agent and the principal bear the same risk in the contract.

# Asymmetric Information

- The principal **cannot observe** the agent's effort level  $e$ .
- The principal needs to offer to the agent enough incentives to exert the profit-maximizing effort level.
- How can the principal achieve this objective?
  - Make the salary an increasing function of the realized profit.
  - This is optimal even if the agent is risk-averse.

# Asymmetric Information

- The principal's problem is

$$\max_{\{e, w(\pi_i)\}_{i=1}^N} \sum_{i=1}^N f(\pi_i | e) \cdot B(\pi_i - w(\pi_i))$$

s.t.  $\sum_{i=1}^N f(\pi_i | e) [u(w(\pi_i)) - g(e)] \geq \bar{u}$

$$e^* \in \arg \max_e \sum_{i=1}^N f(\pi_i | e) [u(w(\pi_i)) - g(e)]$$

- The principal seeks to maximize its expected profits subject to:
  1. The voluntary participation of the agent (PC condition);
  2. The effort that he anticipates the agent will optimally choose in order to maximize his expected utility after receiving the contract from the principal (incentive compatibility, IC, condition).

# Asymmetric Information

- Assume there are only two different effort levels available to the agent ( $e_L$  and  $e_H$ , where  $e_H > e_L$ ).
- The agent can choose to work a positive number of hours or completely slack from the job ( $e_H = e > 0$  and  $e_L = 0$ ).
- Consider that the principal seeks to induce the high effort level  $e_H$  and that the principal is **risk-neutral** while the agent is **risk-averse**.

# Asymmetric Information

- The principal's problem reduces to

$$\max_{\{e, w(\pi_i)\}_{i=1}^N} \sum_{i=1}^N f(\pi_i | e_H) \cdot [\pi_i - w(\pi_i)]$$

$$\text{s.t.} \quad \sum_{i=1}^N f(\pi_i | e_H) [u(w(\pi_i)) - g(e_H)] \geq \bar{u} \quad (\text{PC})$$

$$\sum_{i=1}^N f(\pi_i | e_H) [u(w(\pi_i)) - g(e_H)] \geq \sum_{i=1}^N f(\pi_i | e_L) [u(w(\pi_i)) - g(e_L)] \quad (\text{IC})$$

where the IC condition induces the agent to choose effort level  $e_H$  as such effort yields a higher expected utility than  $e_L$  for the agent.

# Asymmetric Information

- The Lagrangian becomes

$$\begin{aligned}\mathcal{L} = & \sum_{i=1}^N f(\pi_i | e_H) \cdot [\pi_i - w(\pi_i)] \\ & + \lambda \left[ \sum_{i=1}^N f(\pi_i | e_H) [u(w(\pi_i)) - g(e_H)] - \bar{u} \right] \\ & + \mu \left\{ \sum_{i=1}^N f(\pi_i | e_H) [u(w(\pi_i)) - g(e_H)] \right. \\ & \left. - \left[ \sum_{i=1}^N f(\pi_i | e_L) [u(w(\pi_i)) - g(e_L)] \right] \right\}\end{aligned}$$

# Asymmetric Information

- Taking FOC with respect to  $w$  yields

$$\begin{aligned} & -f(\pi_i | e_H) + \lambda f(\pi_i | e_H) u'(w(\pi_i)) \\ & + \mu [f(\pi_i | e_H) u'(w(\pi_i)) - f(\pi_i | e_L) u'(w(\pi_i))] = 0 \end{aligned}$$

- Rearranging

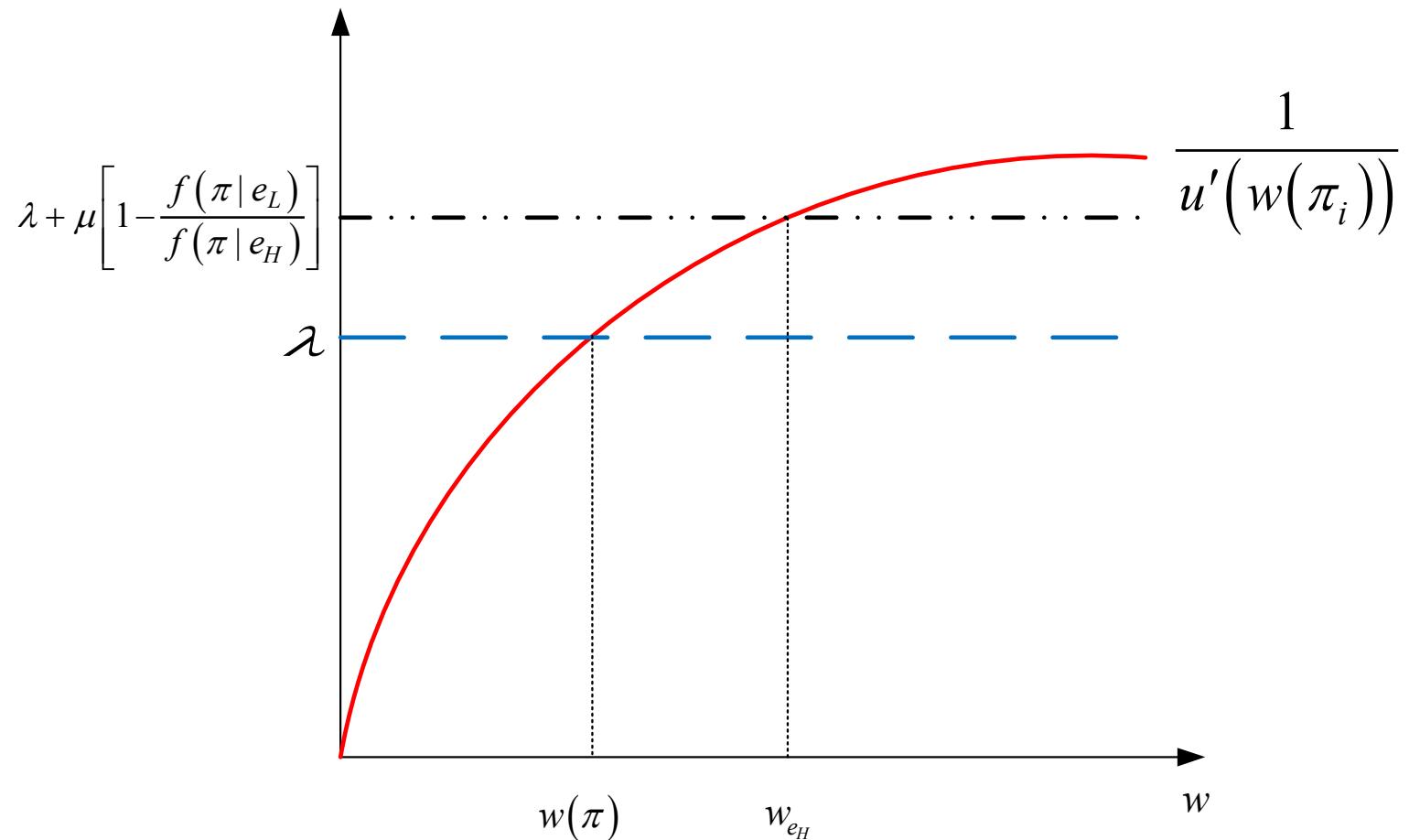
$$\underbrace{\lambda + \mu \left[ 1 - \frac{f(\pi_i | e_L)}{f(\pi_i | e_H)} \right]}_{\text{New}} = \frac{1}{u'(w(\pi_i))} \quad (6)$$

- Compare (6) with expression (2) in case 1, where the principal was risk-neutral but the agent was risk-averse.

# Asymmetric Information

- Because  $\lambda > 0$ ,  $\mu > 0$ , and  $\frac{f(\pi_i|e_L)}{f(\pi_i|e_H)} < 1$ , then
$$\underbrace{\lambda + \mu \left[ 1 - \frac{f(\pi_i|e_L)}{f(\pi_i|e_H)} \right]}_{\text{asymmetric info.}} > \underbrace{\lambda}_{\text{symmetric info.}}$$

# Asymmetric Information



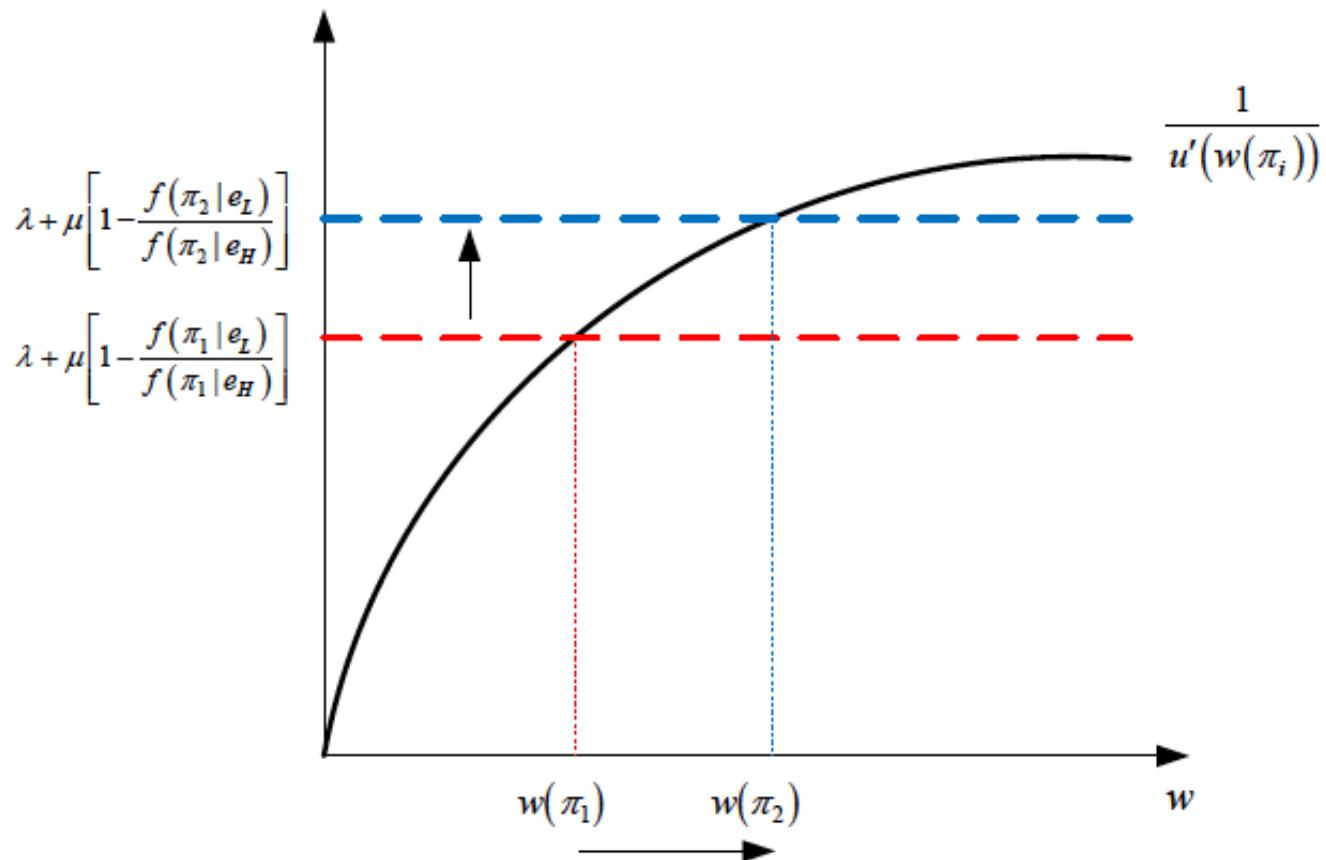
# Asymmetric Information

- When deciding which effort to implement, the principal compares the effects of inducing a high effort level  $e_H$ .
  - Effort  $e_H$  yields a **positive effect** on profits since it increases the likelihood of higher profits.
  - This positive effect emerges under both symmetric and asymmetric information.
  - Effort  $e_H$  also entails a **negative effect** on profits since the salary that induces such effort is higher under asymmetric than under symmetric information  $w_{e_H} > w(\pi)$ .
  - Hence the principal is less willing to induce  $e_H$  when the agent's effort is unobservable than when it is observable.

# Comparative Statics

- How does the salary above change as a function of the profit realization?
  - For that to happen, the left-hand side of (6) needs to increase in  $\pi$ .
  - This occurs if the likelihood ratio  $\frac{f(\pi_i|e_L)}{f(\pi_i|e_H)}$  decreases in  $\pi$ .
  - Intuitively, as profits increase, the likelihood of obtaining a profit level of  $\pi$  from effort  $e_H$  increases faster than the probability of obtaining such a profit level from  $e_L$ .
  - This probability is commonly known as the **monotone likelihood ratio property**, MLRP.

# Comparative Statics



# Comparative Statics

- **Example 2:**
  - Consider Example 1, but assuming that the principal cannot observe the agent's effort.
  - In this incomplete information setting, the principal must offer a salary that increases in profit if he seeks to induce  $e_H = 5$ .
  - The principal's maximization problem becomes

$$\max_{\{w(\pi_i)\}_{i=1}^3} 270 - [0.1w(\pi_1) + 0.3w(\pi_2) + 0.6w(\pi_3)]$$

$$\text{s.t. } 0.1\sqrt{w(\pi_1)} + 0.3\sqrt{w(\pi_2)} + 0.6\sqrt{w(\pi_3)} - 5 \geq 9 \quad (\text{PC})$$

$$\begin{aligned} 0.1\sqrt{w(\pi_1)} + 0.3\sqrt{w(\pi_2)} + 0.6\sqrt{w(\pi_3)} - 5 &\geq \\ 0.6\sqrt{w(\pi_1)} + 0.3\sqrt{w(\pi_2)} + 0.1\sqrt{w(\pi_3)} & \end{aligned} \quad (\text{IC})$$

# Comparative Statics

- Example 2: (con't)
  - Since the principal's revenue is a constant (\$270), he can alternatively minimize his expected costs

$$\min_{\{w(\pi_i)\}_{i=1}^3} 0.1w(\pi_1) + 0.3w(\pi_2) + 0.6w(\pi_3)$$

$$\text{s.t. } 0.1\sqrt{w(\pi_1)} + 0.3\sqrt{w(\pi_2)} + 0.6\sqrt{w(\pi_3)} - 14 \geq 0 \quad (\text{PC})$$

$$-0.5\sqrt{w(\pi_1)} + 0.5\sqrt{w(\pi_3)} - 5 \geq 0 \quad (\text{IC})$$

where the IC constraint has been simplified.

# Comparative Statics

- **Example 2:** (con't)

- The associated Lagrangian is

$$\begin{aligned}\mathcal{L} = & 0.1w(\pi_1) + 0.3w(\pi_2) + 0.6w(\pi_3) \\ & - \lambda \left[ 0.1\sqrt{w(\pi_1)} + 0.3\sqrt{w(\pi_2)} + 0.6\sqrt{w(\pi_3)} - 14 \right] \\ & - \mu \left[ -0.5\sqrt{w(\pi_1)} + 0.5\sqrt{w(\pi_3)} - 5 \right]\end{aligned}$$

- Taking FOC with respect to  $w(\pi_1)$ ,  $w(\pi_2)$ , and  $w(\pi_3)$  yields

$$\frac{\partial \mathcal{L}}{\partial w(\pi_1)} = 0.1 - \frac{0.1\lambda}{2\sqrt{w(\pi_1)}} + \frac{0.5\mu}{2\sqrt{w(\pi_1)}} = 0 \quad (7)$$

$$\frac{\partial \mathcal{L}}{\partial w(\pi_2)} = 0.3 - \frac{0.3\lambda}{2\sqrt{w(\pi_2)}} = 0 \quad (8)$$

$$\frac{\partial \mathcal{L}}{\partial w(\pi_3)} = 0.6 - \frac{0.6\lambda}{2\sqrt{w(\pi_3)}} - \frac{0.5\mu}{2\sqrt{w(\pi_3)}} = 0 \quad (9)$$

# Comparative Statics

- Example 2: (con't)

- Rearranging (7) and (8)

$$\lambda = 2\sqrt{w(\pi_2)}$$

$$\mu = 0.4\sqrt{w(\pi_2)} - 0.4\sqrt{w(\pi_1)}$$

- Plugging these values into (9) and rearranging

$$0.1\sqrt{w(\pi_1)} - 0.7\sqrt{w(\pi_2)} + 0.6\sqrt{w(\pi_3)} = 0 \quad (10)$$

- Combining equation (10) with the (PC) and (IC) equations, we have three equations and three unknowns  $w(\pi_1)$ ,  $w(\pi_2)$ , and  $w(\pi_3)$ .

# Comparative Statics

- **Example 2:** (con't)

- The (IC) equation yields

$$\sqrt{w(\pi_3)} = 10 + \sqrt{w(\pi_1)}$$

- Substituting this into the (PC) equation

$$3\sqrt{w(\pi_2)} = 80 - 7\sqrt{w(\pi_1)}$$

- Last, substituting the values of  $w(\pi_2)$  and  $w(\pi_3)$  in equation **(10)**

$$w(\pi_1) = \$29.47, w(\pi_2) = \$196, w(\pi_3) = \$238.04$$

- The principal's expected profit is then

$$270 - [0.1 \cdot 29.47 + 0.3 \cdot 196 + 0.6 \cdot 238.04] = \$65.43$$

which is lower than its profit when effort is observable (\$74).

# Moral Hazard with a Continuum of Effort Levels—The First-Order Approach

# Continuum of Effort Levels

- So far we assumed that a worker could only have a discrete number of effort levels.
- Let us now consider a continuum of effort levels.
- The principal seeks to maximize its expected profits by anticipating the effort level that the agent selects in the second stage of the game:

$$\max_{\{e, w(\pi_i)\}_{i=1}^N} \sum_{i=1}^N f(\pi_i | e) \cdot [\pi_i - w(\pi_i)]$$

$$\text{s.t. } \sum_{i=1}^N f(\pi_i | e) u(w(\pi_i)) - g(e) \geq \bar{u} \quad (\text{PC})$$

$$e^* \in \arg \max_e \sum_{i=1}^N f(\pi_i | e) [u(w(\pi_i)) - g(e)] \quad (\text{IC})$$

# Continuum of Effort Levels

- Difference/similarities between discrete and continuum effort levels
  - The objective function of the principal and the PC condition for the agent coincide.
  - The agent's IC condition, however, differs as it now allows him to choose among a continuum of effort levels.
  - Intuitively, the IC condition represents the agent's UMP where, for a given salary  $w(\pi_i)$ , the agent selects an effort level  $e$  that maximizes his expected utility.

# Continuum of Effort Levels

- Differentiating the agent's expected utility with respect to  $e$  yields

$$\sum_{i=1}^N f'(\pi_i | e) u(w(\pi_i)) - g'(e) = 0$$

- The agent's FOC above can be used as the IC condition in the principal's problem.
- This approach is known as the **first-order approach**.

# Continuum of Effort Levels

- The principal's problem, using a "first-order approach," is then

$$\max_{\{e, w(\pi_i)\}_{i=1}^N} \sum_{i=1}^N f(\pi_i | e) \cdot [\pi_i - w(\pi_i)]$$

$$\text{s.t.} \quad \sum_{i=1}^N f(\pi_i | e) u(w(\pi_i)) - g(e) \geq \bar{u} \quad (\text{PC})$$

$$\sum_{i=1}^N f'(\pi_i | e) u(w(\pi_i)) - g'(e) = 0 \quad (\text{IC})$$

# Continuum of Effort Levels

- The the Lagrangian becomes

$$\begin{aligned}\mathcal{L} = & \sum_{i=1}^N f(\pi_i | e) \cdot [\pi_i - w(\pi_i)] \\ & + \lambda \left[ \sum_{i=1}^N f(\pi_i | e) u(w(\pi_i)) - g(e) - \bar{u} \right] \\ & + \mu \left[ \sum_{i=1}^N f'(\pi_i | e) u(w(\pi_i)) - g'(e) \right]\end{aligned}$$

- Taking FOC with respect to  $w$  yields

$$\begin{aligned}\frac{\partial \mathcal{L}}{\partial w} = & -f(\pi_i | e) + \lambda f(\pi_i | e) u'(w(\pi_i)) \\ & + \mu f'(\pi_i | e) u'(w(\pi_i)) = 0\end{aligned}$$

# Continuum of Effort Levels

- Dividing both sides by  $f(\pi_i|e)$

$$-1 + \lambda u'(w(\pi_i)) + \mu \frac{f'(\pi_i|e)}{f(\pi_i|e)} u'(w(\pi_i)) = 0$$

- Factoring out  $u'(w(\pi_i))$  on the left-hand side and rearranging

$$\lambda + \mu \frac{f'(\pi_i|e)}{f(\pi_i|e)} = \frac{1}{u'(w(\pi_i))}$$

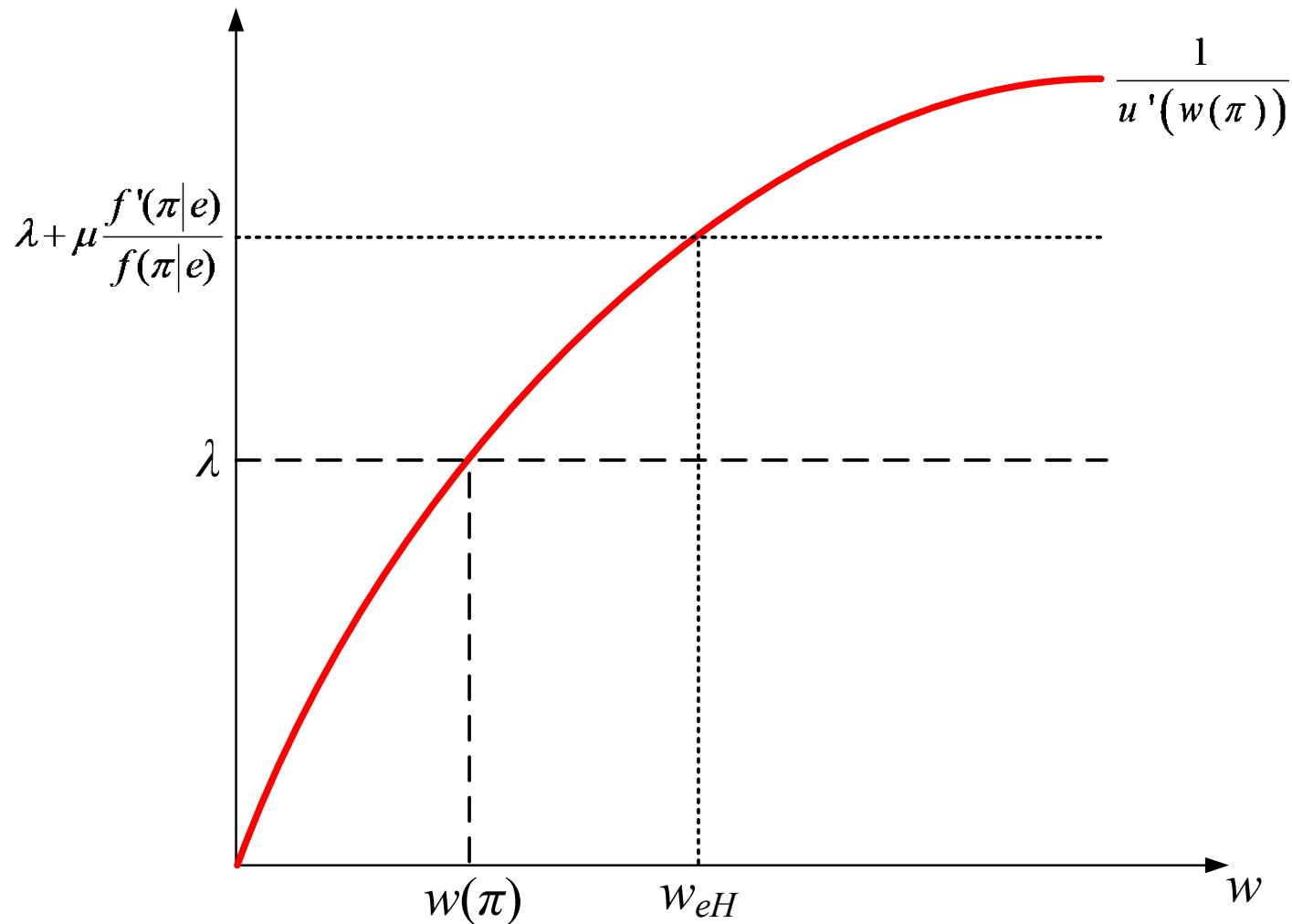
- This result is similar to that in previous sections.
- Because  $\lambda > 0$  and  $\mu > 0$  (since PC and IC bind), the left-hand side satisfies

$$\lambda + \mu \frac{f'(\pi_i|e)}{f(\pi_i|e)} > \lambda$$

# Continuum of Effort Levels

- Since  $u'$  is decreasing in  $w$  (by concavity), its inverse,  $1/u'$ , is increasing in  $w$ .
- Hence the principal offers a larger salary under asymmetric information than symmetric information.
- $\frac{f'(\pi_i|e)}{f(\pi_i|e)}$  is the likelihood ratio, which measures how a marginally higher effort entails a larger probability of obtaining a given profit level  $\pi_i$  relative to an initial effort level.

# Continuum of Effort Levels



# Continuum of Effort Levels

- Taking FOC with respect to  $e$  yields

$$\begin{aligned}\frac{\partial \mathcal{L}}{\partial e} = & \sum_{i=1}^N f'(\pi_i|e) \cdot [\pi_i - w(\pi_i)] + \mu \left[ \sum_{i=1}^N f''(\pi_i|e) u(w(\pi_i)) - g''(e) \right] \\ & + \lambda \left[ \sum_{i=1}^N f'(\pi_i|e) u(w(\pi_i)) - g'(e) \right] = 0\end{aligned}$$

- Rearranging

$$\begin{aligned}\sum_{i=1}^N f'(\pi_i|e) \pi_i = & \sum_{i=1}^N f'(\pi_i|e) w(\pi_i) \\ & - \mu \left[ \sum_{i=1}^N f''(\pi_i|e) u(w(\pi_i)) - g''(e) \right] \\ & - \lambda \left[ \sum_{i=1}^N f'(\pi_i|e) u(w(\pi_i)) - g'(e) \right]\end{aligned}$$

(11)

- Intuitively, effort is increased until the point where its expected profits (left-hand side) coincide with its associated costs (right-hand side).

# Continuum of Effort Levels

- The cost of inducing a higher effort originates from two sources:
  1. A higher effort increases the probability of obtaining a higher profit, and thus the salary that the principal pays the agent once the profit is realized (first term on the right-hand side).
  2. The principal must provide more incentives (higher salary) in order for the agent to exert the effort level that the principal intended (second term on the right-hand side).

# Continuum of Effort Levels

- Example 3:
  - Moral hazard with continuous effort but only two possible outcomes.
  - Consider a setting in which the conditional probability satisfies
$$f(\pi_i|e) = ef_H(\pi_i) + (1 - e)f_L(\pi_i), \quad e \in [0,1]$$
  - When effort is relatively high  $e \rightarrow 1$ , the probability of obtaining a profit level  $\pi_i$  is  $f_H(\pi_i)$ , where  $f_H(\pi_i) > f_L(\pi_i)$ .
  - When  $e \rightarrow 0$ , the probability of obtaining a profit level  $\pi_i$  is  $f_L(\pi_i)$ .

# Continuum of Effort Levels

- **Example 3:** (con't)

- The agent's expected utility is

$$EU(e) = \sum_{i=1}^N [ef_H(\pi_i) + (1 - e)f_L(\pi_i)]u(w(\pi_i)) - g(e)$$

- Since

$$ef_H(\pi_i) + (1 - e)f_L(\pi_i) = e[f_H(\pi_i) - f_L(\pi_i)] + f_L(\pi_i)$$

- Then

$$\begin{aligned} EU(e) &= \sum_{i=1}^N e[f_H(\pi_i) - f_L(\pi_i)]u(w(\pi_i)) \\ &\quad + \sum_{i=1}^N f_L(\pi_i)u(w(\pi_i)) - g(e) \end{aligned}$$

- Differencing  $EU(e)$  twice with respect to effort  $e$ , yields  $-g''(e)$ , which is negative by definition.
  - So we can use the first-order approach.

# Continuum of Effort Levels

- Example 3: (con't)

- The agent's FOC with respect to  $e$  is

$$\sum_{i=1}^N [f_H(\pi_i) - f_L(\pi_i)]u(w(\pi_i)) = g'(e)$$

- Plugging this FOC into the principal's problem

$$\max_{\{e, w(\pi_i)\}_{i=1}^N} \sum_{i=1}^N [ef_H(\pi_i) + (1 - e)f_L(\pi_i)] \cdot [\pi_i - w(\pi_i)]$$

$$\text{s.t. } \sum_{i=1}^N [ef_H(\pi_i) + (1 - e)f_L(\pi_i)] u(w(\pi_i)) - g(e) \geq \bar{u} \quad (\text{PC})$$

$$\sum_{i=1}^N [f_H(\pi_i) - f_L(\pi_i)]u(w(\pi_i)) = g'(e) \quad (\text{IC})$$

# Continuum of Effort Levels

- Example 3: (con't)
  - The Lagrangian of this program is

$$\begin{aligned}\mathcal{L} = & \sum_{i=1}^N [ef_H(\pi_i) + (1 - e)f_L(\pi_i)] \cdot [\pi_i - w(\pi_i)] \\ & + \lambda \left[ \sum_{i=1}^N [ef_H(\pi_i) + (1 - e)f_L(\pi_i)] u(w(\pi_i)) - g(e) - \bar{u} \right] \\ & + \mu \left[ \sum_{i=1}^N [f_H(\pi_i) - f_L(\pi_i)] u(w(\pi_i)) - g'(e) \right]\end{aligned}$$

- Taking FOC with respect to  $w$  and rearranging

$$\lambda + \mu \frac{f_H(\pi_i) - f_L(\pi_i)}{ef_H(\pi_i) + (1 - e)f_L(\pi_i)} = \frac{1}{u'(w(\pi_i))}$$

# Continuum of Effort Levels

- Example 3: (con't)

- Taking FOC with respect to  $e$  and rearranging

$$\begin{aligned} & \sum_{i=1}^N [f_H(\pi_i) - f_L(\pi_i)] \pi_i \\ &= \sum_{i=1}^N [f_H(\pi_i) - f_L(\pi_i)] w(\pi_i) + \mu g''(e) \\ & - \lambda \left[ \sum_{i=1}^N [f_H(\pi_i) - f_L(\pi_i)] u(w(\pi_i)) - g'(e) \right] \end{aligned}$$

# Continuum of Effort Levels

- Example 3: (con't)
  - From the binding (IC), we can further simplify and obtain
$$\sum_{i=1}^N [f_H(\pi_i) - f_L(\pi_i)] \pi_i = \sum_{i=1}^N [f_H(\pi_i) - f_L(\pi_i)] w(\pi_i) + \mu g''(e)$$
  - The expected profit to the principal (left-hand side) is exactly balanced by the expected cost of inducing effort  $e$  from the agent (right-hand side).

# Continuum of Effort Levels

- Example 4:
  - Moral hazard using the first-order approach
  - Assume the expected utility function of the agent is

$$u(w, e) = E(w) - \frac{1}{2} \rho \text{Var}(w) - c(e)$$

where:

- $\rho$  is the Arrow–Pratt coefficient of absolute risk aversion for utility function  $u(w) = -e^{-\rho w}$ ,
- $e \in [0,1]$  is the agent's effort, and
- $c(e) = 0.5e^2$  is the cost of effort.
- The outcome of the project,  $x$ , is stochastic and given by  
$$x = f(e, \varepsilon) = e + \varepsilon, \text{ where } \varepsilon \sim N(0, \sigma^2)$$

# Continuum of Effort Levels

- Example 4: (con't)
  - The agent's reservation utility is  $\bar{u} = \frac{1}{2}$ .
  - The principal offers a linear contract to the agent
$$w(x) = a + bx$$
  - where  $a > 0$  is a fixed payment, and  $b \in [0,1]$  is the share of profits that the agent receives (bonus).
  - The principal's expected profits are
$$\begin{aligned}E(\pi) &= E(x - w) = E(x) - E(w) \\&= E(x) - [a + bE(x)] = (1 - b)e - a\end{aligned}$$

# Continuum of Effort Levels

- Example 4: (con't)
  - Since  $E(x) = e$ , the expected utility of the agent when he exerts effort level  $e$  is

$$\begin{aligned}E[u(w, e)] &= E(w) - \frac{1}{2}\rho Var(w) - c(e) \\&= a + be - \frac{1}{2}\rho b^2 \sigma^2 - \frac{1}{2}e^2\end{aligned}$$

where  $E(w) = a + be$ ,  $Var(w) = b^2 \sigma^2$ , and  $c(e) = \frac{1}{2}e^2$ .

# Continuum of Effort Levels

- **Example 4:** (con't)
  - Taking FOC with respect to  $e$ , we can find the effort that the agent chooses
$$\frac{\partial E[u(w, e)]}{\partial e} = b - e = 0$$
$$e = b$$
  - The principal's problem is to choose the fixed payment,  $a$ , and the bonus,  $b$ , to solve

$$\max_{e,a,b} (1 - b)e - a$$

$$\text{s.t.} \quad a + be - \frac{1}{2}\rho b^2 \sigma^2 - \frac{1}{2}e^2 \geq \frac{1}{2} \quad (\text{PC})$$
$$e = b \quad (\text{IC})$$

# Continuum of Effort Levels

- Example 4: (con't)

- Plugging  $e = b$  into the program and simplifying

$$\max_{a,b} (1 - b)b - a$$

$$\text{s.t. } a + \frac{1}{2}b^2(1 - \rho\sigma^2) \geq \frac{1}{2} \quad (\text{PC})$$

- The Lagrangian is

$$\mathcal{L} = (1 - b)b - a + \lambda \left[ a + \frac{1}{2}b^2(1 - \rho\sigma^2) - \frac{1}{2} \right]$$

# Continuum of Effort Levels

- Example 4: (con't)
  - The first order conditions are

$$\frac{\partial \mathcal{L}}{\partial a} = -1 + \lambda = 0 \rightarrow \lambda = 1 \quad (12)$$

$$\frac{\partial \mathcal{L}}{\partial b} = 1 - 2b + \lambda b(1 - \rho\sigma^2) = 0 \quad (13)$$

$$\frac{\partial \mathcal{L}}{\partial \lambda} = a + \frac{1}{2}b^2(1 - \rho\sigma^2) - \frac{1}{2} = 0 \quad (14)$$

- Plugging (12) into (13) yields

$$1 - 2b + b(1 - \rho\sigma^2) = 0$$

$$b = \frac{1}{1 + \rho\sigma^2}$$

# Continuum of Effort Levels

- Example 4: (con't)

- Plugging  $b = \frac{1}{1+\rho\sigma^2}$  into the binding (PC) constraint yields

$$a + \frac{1 - \rho\sigma^2}{2(1 + \rho\sigma^2)^2} = \frac{1}{2}$$

- Solving for the fixed payment  $a$

$$a = \frac{1}{2} \left[ 1 - \frac{1 - \rho\sigma^2}{(1 + \rho\sigma^2)^2} \right]$$

# Continuum of Effort Levels

- Example 4: (con't)
  - If  $\sigma^2 = 0$ , effort  $e$  is deterministic (a perfect predictor of profits)

$$x = f(e) = e$$

- Then,

$$b = \frac{1}{1 + \rho \cdot 0} = 1$$

$$a = \frac{1}{2} \left[ 1 - \frac{1 - \rho \cdot 0}{(1 + \rho \cdot 0)^2} \right] = 0$$

- Intuitively, the principal does not offer a fixed payment, and the agent is benefited from high-powered incentives.

# Continuum of Effort Levels

- Example 4: (con't)
  - If  $\sigma^2 = 1$ , effort  $e$  is imprecise predictor of outcomes.
  - Then,

$$b = \frac{1}{1 + \rho}$$
$$a = \frac{\rho(\rho + 3)}{2(1 + \rho)^2}$$

# Continuum of Effort Levels

- Example 4: (con't)
  - When the agent becomes more risk-averse ( $\rho$  increases), the agent is offered a higher fixed payment but a lower bonus, since

$$\frac{\partial b}{\partial \rho} = -\frac{1}{(1 + \rho)^2} < 0$$

$$\frac{\partial a}{\partial \rho} = \frac{3 - \rho}{2(1 + \rho)^3} > 0$$

# Continuum of Effort Levels

- Example 4: (con't)
  - In general, for  $0 \leq \sigma^2 \leq 1$ , we show that  $a$  increases but  $b$  decreases in  $\sigma^2$  since

$$\frac{\partial b}{\partial \sigma^2} = -\frac{\rho}{(1 + \rho\sigma^2)^2} < 0$$
$$\frac{\partial a}{\partial \sigma^2} = -\frac{-\rho(1 + \rho\sigma^2)^2 - 2\rho(1 + \rho\sigma^2)(1 - \rho\sigma^2)}{2(1 + \rho\sigma^2)^4}$$
$$= \frac{\rho(3 - \rho\sigma^2)}{2(1 + \rho\sigma^2)^3} > 0$$

# Continuum of Effort Levels

- Example 4: (con't)
- When  $\sigma^2$  is low (i.e., all effort levels yield a similar outcome  $x$ ), the fixed payment  $a$  is low while the bonus  $b$  is high, which we call **high-powered incentives**.
- When  $\sigma^2$  is high (i.e., an effort level is possible to yield many different outcomes  $x$ ), the fixed payment  $a$  is high while the bonus  $b$  is low, which we call **low-powered incentives**.

# Moral Hazard with Multiple Signals

# Multiple Signals

- Consider a setting in which the principal, still not observing effort  $e$ , observes:
  - the profits  $\pi$  of the firm;
  - a signal  $s$ , based on a middle management report about the agent's performance.
- Signal  $s$  provides no intrinsic economic value but it provides information about effort  $e$ .
- Hence the probability density function has two observables,  $\pi$  and  $s$ .
- Then, similar to equation (6), we have

$$\frac{1}{u'(w)} = \gamma + \mu \left[ 1 - \frac{f(\pi, s | e_L)}{f(\pi, s | e_H)} \right]$$

# Multiple Signals

- Hence variations in  $s$  affect wages only if  $f(\pi, s|e) \neq f(\pi|e)$
- That is, if  $\pi$  is not a sufficient statistic of  $e$ .
- Intuitively, the pair  $(\pi, s)$  contains more information about the agent's exerted effort  $e$  than  $\pi$  alone.
- Signal  $s$  is uninformative (provides no more information than  $\pi$  alone), if  $f(\pi, s|e) = f(\pi|e)$
- We can examine under which conditions  $w$  increases in signal  $s$ .

# Multiple Signals

- For two signals  $s_1$  and  $s_2$ , where  $s_2 > s_1$ , if salary increases in the signal,  $w(\pi, s_2) > w(\pi, s_1)$ , then  $u'(w)$  decreases and its inverse,  $1/u'(w)$ , increases.
- Therefore,

$$\gamma + \mu \left[ 1 - \frac{f(\pi, s_2 | e_L)}{f(\pi, s_2 | e_H)} \right] > \gamma + \mu \left[ 1 - \frac{f(\pi, s_1 | e_L)}{f(\pi, s_1 | e_H)} \right]$$

- Simplifying this inequality to express it in terms of the likelihood ratio,  $\frac{f(\pi, s | e_L)}{f(\pi, s | e_H)}$ , we obtain

$$\frac{f(\pi, s_2 | e_L)}{f(\pi, s_2 | e_H)} < \frac{f(\pi, s_1 | e_L)}{f(\pi, s_1 | e_H)}$$

- In words, this condition says that, for the salary to increase in the intermediate signal  $s$  that the principal receives, we need such a signal to have a *decreasing* likelihood ratio.

# Multiple Signals

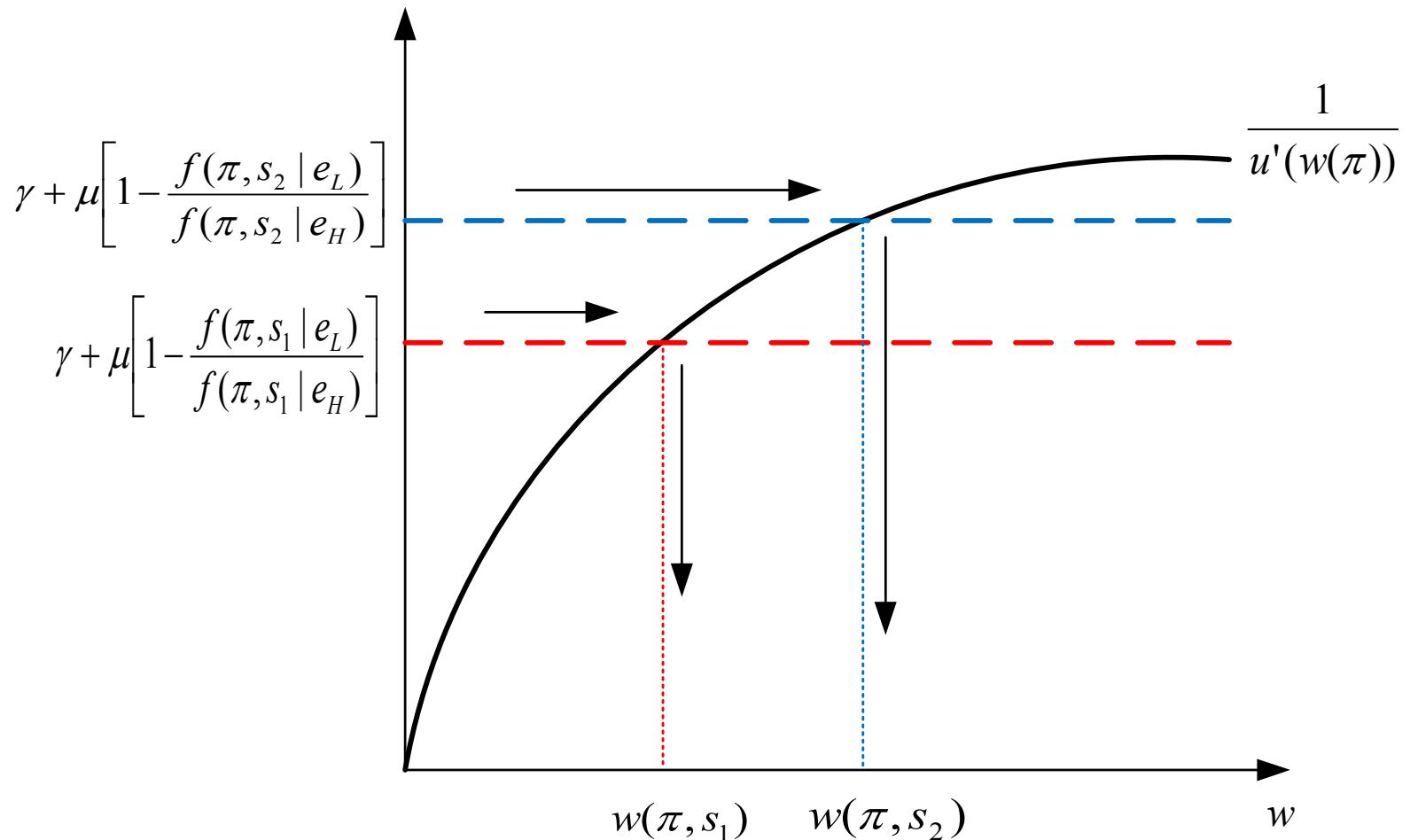
- Alternatively, we can rearrange expression

$$\frac{f(\pi, s_2 | e_L)}{f(\pi, s_2 | e_H)} < \frac{f(\pi, s_1 | e_L)}{f(\pi, s_1 | e_H)} \text{ as follows}$$

$$\frac{f(\pi, s_1 | e_H)}{f(\pi, s_1 | e_L)} < \frac{f(\pi, s_2 | e_H)}{f(\pi, s_2 | e_L)}$$

- Intuitively, signal  $s_2$  is more likely to originate from the high than the low effort, relative to signal  $s_1$ .

# Multiple Signals



# Adverse Selection The “Lemons” Problem

# Adverse Selection

- **Adverse selection**: settings in which an agent does not observe the payoff of the other individual.
  - Also referred to as “hidden information”
- Example:
  - A manager in a firm might not observe the worker’s ability
  - The manager could err in its selection of candidates for a job if he does not observe their ability, thus giving rise to adverse selection
- Under symmetric information markets often work well.
- Under asymmetric information, however, markets do not necessarily work well.

# Adverse Selection

- Akerloff's (1970) model:
  - Consider a market of used cars, whose quality is denoted by  $q$ , where  $q \in U[0, Q]$  and  $Q \in (1,2)$ .
  - A car of quality  $q$  is valued as such by the buyer, and as  $q/Q$  by the seller.
  - Since  $\frac{q}{Q} < q$ , the buyer assigns a higher value to the car than the seller.
  - This allows both parties to exchange the car at a price  $p$  between  $q/Q$  and  $q$  and make a profit (for the seller) and a surplus (for the buyer).

# Adverse Selection

- Akerloff's (1970) model:
  - If a car of quality  $q$  is exchanged at price  $p$  the buyer obtains a utility
$$u(p, q) = q - p$$
while the seller makes a profit of
$$\pi(p, q, Q) = p - \frac{q}{Q}$$
  - Assume that there are a sufficient number of buyers so that all gains from trade are appropriated by the seller.

# Symmetric Information

- When the buyer can **perfectly** observe the car quality  $q$ , he buys at a price  $p$  if and only if

$$q - p \geq 0$$

- That is, his utility from such a trade is positive.
- A seller with a car of quality  $q$  anticipates such an acceptance rule by the buyer and sets a price  $p$  that solves

$$\begin{aligned} \max_{p \geq 0} \quad & p - \frac{q}{Q} \\ \text{s.t.} \quad & p \leq q \end{aligned}$$

where  $p \leq q$  is the buyer's participation constraint (PC).

# Symmetric Information

- Since condition (PC) must bind,  $p = q$ , the seller's objective function can be represented as unconstrained problem:

$$\max_{p \geq 0} p - \frac{p}{Q}$$

- Taking the FOC with respect to  $p$  yields

$$1 - \frac{1}{Q} > 0 \text{ or } \frac{Q-1}{Q} > 0$$

- Since  $Q > 1$  by definition, a corner solution exists whereby the seller raises the price  $p$  as much as possible

$$p^{SI} = q$$

# Asymmetric Information

- When the buyer is **unable** to observe the car's true quality  $q$ , he forms an expectation  $E(q)$ .
- The buyer accepts a trade if the car's asking price  $p$  satisfies

$$p = E(q)$$

- The seller anticipates such an acceptance rule by the buyer and sets a price  $p$  that solves

$$\begin{aligned} \max_{p \geq 0} \quad & p - \frac{q}{Q} \\ \text{s.t.} \quad & p \leq E(q) \end{aligned}$$

where  $p \leq E(q)$  is the buyer's PC constraint.

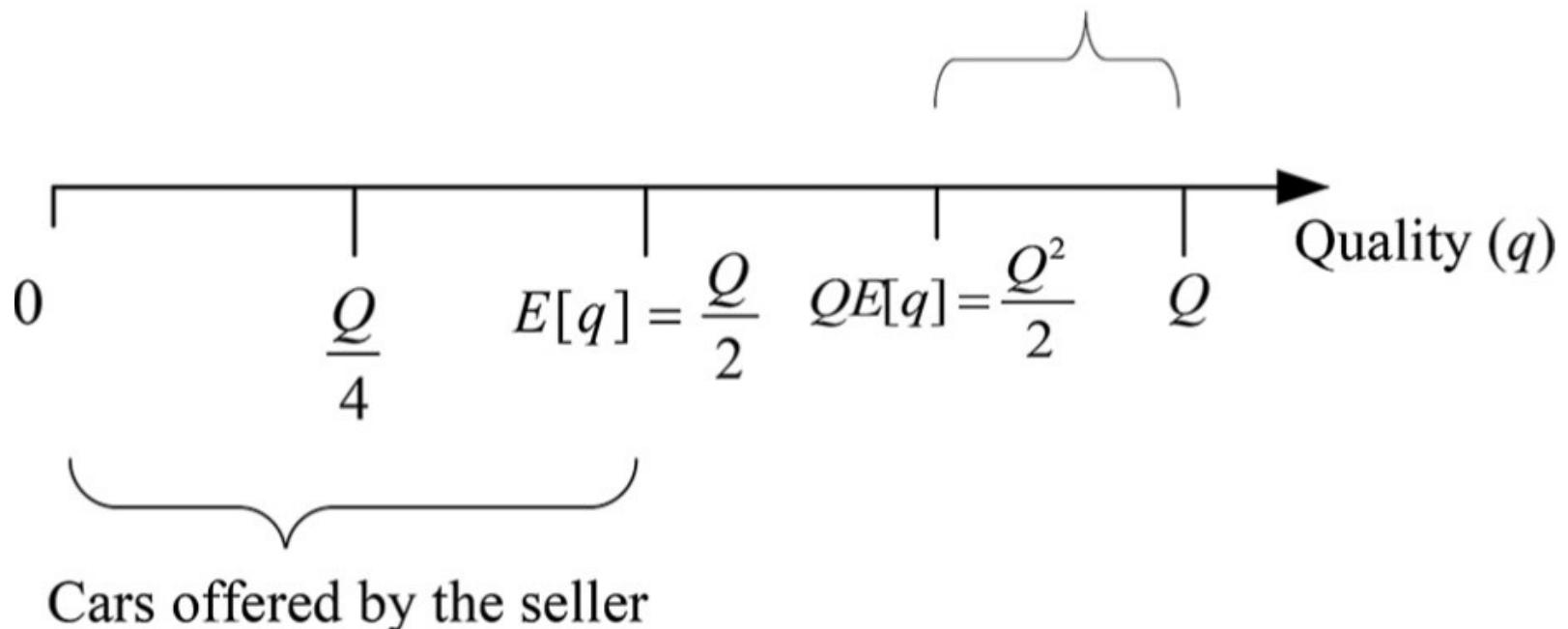
# Asymmetric Information

- Since condition (PC) must bind,  $p = E(q)$ , the price that the seller sets

$$p - \frac{q}{Q} = E(q) - \frac{q}{Q} \geq 0$$
$$q \leq Q \cdot E(q)$$

# Asymmetric Information

Cars *not* offered by the seller (market failure)



# Asymmetric Information

- When  $q$  is uniformly distributed, that is,  $q \sim U[0, Q]$ , its expected value becomes

$$E(q) = \frac{Q - 0}{2} = \frac{Q}{2}$$

- Then,  $Q \cdot E(q) = Q^2/2$ .
- Hence all cars with relatively **low quality**,  $q \leq Q^2/2$ , are offered by the seller at a price

$$p = E(q) = \frac{Q}{2}$$

yielding profit of  $\frac{Q}{2} - \frac{q}{2}$  for the seller and a zero (expected) utility for the buyer since  $p = E(q)$ .

# Asymmetric Information

- Cars with relatively **high quality**,  $q \geq Q^2/2$ , are not offered by the seller since the highest price he can charge to the uninformed buyer,  $p = E(q)$ , does not compensate the seller's costs.
- This is problematic.
- The buyer's inability to observe  $q$  leads to the non-existence of the market for good cars ("peaches"), whereas only bad cars ("lemons") exist in the market.

# Asymmetric Information

- A fully rational buyer would anticipate such a pricing decision by the seller
  - That the seller finds it worthy to only offer low quality cars,  $p \leq Q^2/2$ .
- In that case, the buyer anticipates that only cars of quality  $q \in (0, Q^2/2)$  are offered.
- Then, if  $q \sim U[0, Q]$ , buyers can compute the expected quality of those offered cars

$$E \left[ q \middle| q \leq \frac{Q^2}{2} \right] = \frac{\frac{Q^2}{2} - 0}{2} = \frac{Q^2}{4}$$

# Asymmetric Information

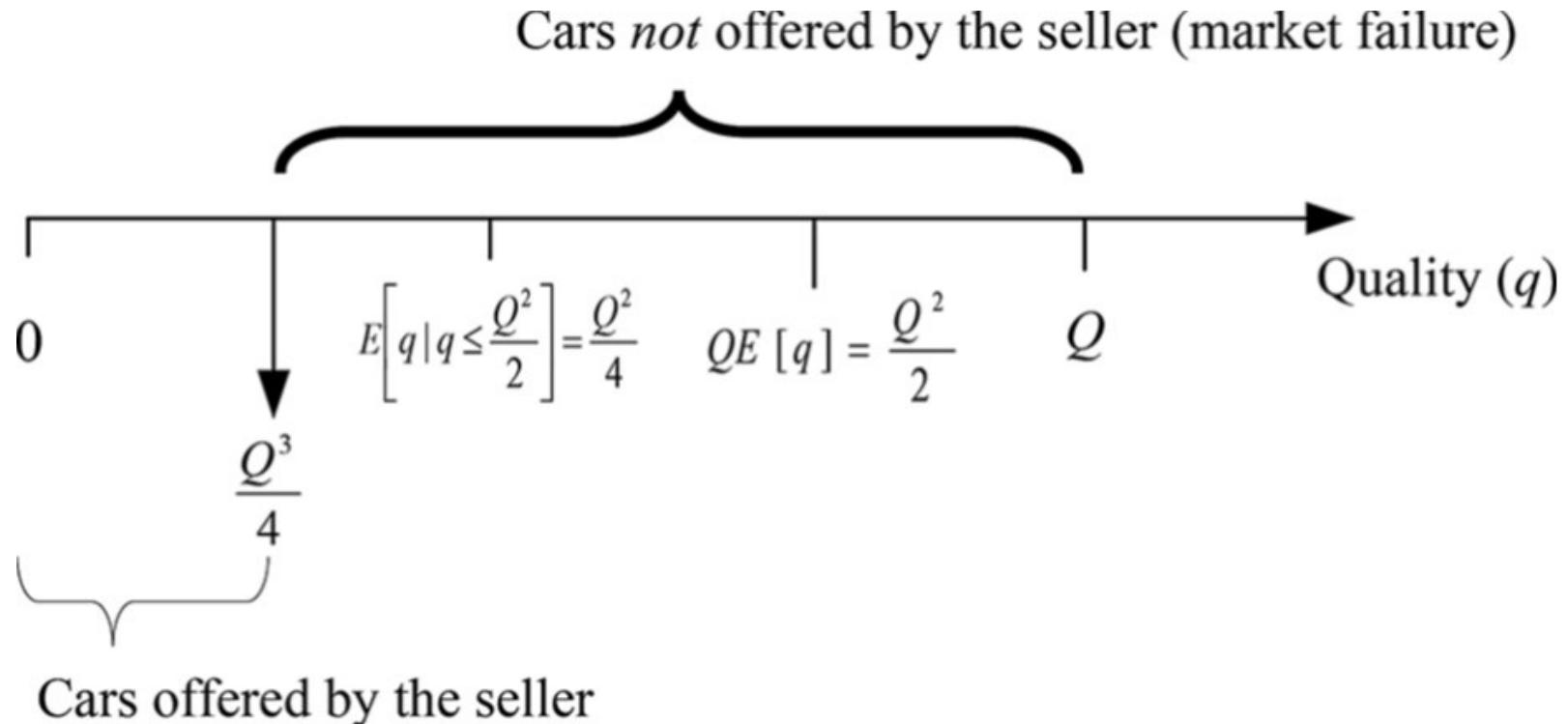
- Hence the buyer would only buy cars whose price satisfies  $p = Q^2/4$ .
- The seller would then set the price at  $p = Q^2/4$ , yielding a profit of

$$p - \frac{q}{Q} = \frac{Q^2}{4} - \frac{q}{Q}$$

which is positive only if quality  $q$  satisfies

$$q \leq \frac{Q^3}{4}$$

# Asymmetric Information



# Asymmetric Information

- A rational buyer would now update its expected car quality to those satisfying  $Q^3/4$
- This yields an expected quality of only

$$E \left[ q \middle| q \leq \frac{Q^3}{4} \right] = \frac{\frac{Q^3}{4} - 0}{2} = \frac{Q^3}{8}$$

- The seller offers cars that yield a positive profit, that is, those with quality  $q$  satisfying

$$p - \frac{q}{Q} = \frac{Q^3}{8} - \frac{q}{Q} \geq 0 \quad \text{or} \quad q \leq \frac{Q^4}{8}$$

which lies closer to zero than cutoff  $\frac{Q^3}{4}$ .

# Asymmetric Information

- Intuition:
  - The seller would shift the set of offered cars even more to the left of the quality line toward worse cars (closer to zero).
  - Repeating the same argument enough times, we find that the market “unravels.”
  - It only offers cars of the worst possible quality,  $q = 0$ .
  - The buyer is only willing to pay a price of  $p = 0$ , leaving all other types of cars unsold.

# Asymmetric Information

- **Example 5:**
  - Consider a market of used cars with maximum available quality  $Q = 1.9$ , and that  $q \sim U[0, Q]$ .
  - Recall that  $Q \in (1,2)$ , i.e., the availability of several cars of relatively good quality.
  - The buyer's expected value is  $\frac{1.9}{2} = 0.95$ .
  - The cutoff  $Q \cdot E(q)$  of cars offered by the seller is  $1.9 \cdot 0.95 = 1.805$ .
  - Unoffered cars  $(1.805, 1.9)$ .
  - Under complete information, these cars would have been bought by the buyer who values them at  $q$ , and sold by the seller who values them at only  $\frac{q}{1.9} = 0.52q$ .

# Asymmetric Information

- **Example 5:** (con't)

- A rational buyer will anticipate that cars in the interval  $(1.805, 1.9)$  are unoffered by the seller.
  - Thus buyer updates expected value of offered cars to

$$E[q|q \leq 1.805] = \frac{1.805 - 0}{2} = 0.9$$

- This leads the seller to only offer those cars with quality
- $$q \leq \frac{Q^3}{4} = 1.71$$
- The set of offered cars is thus restricted from  $(0, 1.805)$  to  $(0, 1.71)$ .
  - A similar argument applies to further iterations in the buyer's expected car quality.
  - The presence of asymmetric information between buyer and seller prevents mutually beneficial trades from occurring.

# Asymmetric Information

- Application to Labor Markets
  - Consider a competitive labor market with many firms seeking to hire a worker for a specific position.
  - The worker (seller of labor services) privately observes his own productivity  $\theta$ , but firms (the buyer of labor) cannot observe it.
  - Firms offer a wage according to the worker's expected productivity

$$E(\theta) = 1/2, \theta \sim U[0,1]$$

- For this salary, only workers with a productivity  $\theta \leq 1/2$  would be interested in accepting the position, while those with  $\theta > 1/2$  will be left unemployed.

# Asymmetric Information

- Application to Labor Markets

- A fully rational manager will only offer a salary of

$$w = E\left(\theta | \theta \leq \frac{1}{2}\right) = \frac{1}{4}$$

- Then only those workers with productivity  $\theta \leq \frac{1}{4}$  accept the job.
  - Extending the argument infinite times, workers with lowest productivity level  $\theta = 0$  are employed, while the labor market for all other worker types  $\theta > 0$  unravels.

# Solutions to Adverse Selection

- The market failure described above can be overcome by a number of tools.
  - Sellers can offer warranties for their cars in order to signal their quality.
  - **Screening:** The principal (buyer) offers a menu of contracts to the agent (seller) that induce each type of agent to voluntarily select only one contract, whereby the contracts induce self-selection.

# Adverse Selection The Principal–Agent Problem

# The Principal–Agent Problem

- Consider a setting where a firm (the principal) seeks to hire a worker (an agent).
- The firm cannot observe the worker's cost of effort
  - This affects the amount of effort that the worker exerts and thus the firm's profits.
- The firm's manager would like to know the worker's cost of effort in order to design his salary.
- The firm's profit function is

$$\pi(e, w) = x(e) - w$$

where  $x(e)$  is the benefit that the firm obtains when the worker supplies  $e$  units of effort,  $x'(e) \geq 0$ ,  $x''(e) \leq 0$ .

# The Principal–Agent Problem

- The worker's utility function is

$$v(w, e|\theta) = u(w) - c(e, \theta)$$

where  $u(w)$  is the value from the salary  $w$ ,  $u'(w) > 0$ ,  $u''(w) \leq 0$ ;  $c(e, \theta)$  is the worker's cost of exerting  $e$  units of effort when his type is  $\theta$ .

- Assume the worker can only be of two types,  $\theta_L$  and  $\theta_H$ , where  $\theta_L < \theta_H$ , with probabilities  $p$  and  $1 - p$ .
- A high-type worker faces a higher total and marginal cost of effort

$$\begin{aligned}c(e, \theta_L) &< c(e, \theta_H) \\c'(e, \theta_L) &< c'(e, \theta_H)\end{aligned}$$

for every  $e$ .

# Symmetric Information

- When the principal (firm) **knows** that the agent is type  $i = \{L, H\}$ , it solves

$$\begin{aligned} & \max_{w_i, e_i} x(e_i) - w_i \\ \text{s.t. } & u(w_i) - c(e_i, \theta_i) \geq 0 \end{aligned} \quad (\text{PC})$$

- (PC) constraint guarantees that the worker willingly accepts the contract.
- Since the firm can reduce  $w_i$  until (PC) holds with equality, (PC) must bind

$$\begin{aligned} u(w_i) &= c(e_i, \theta_i) \\ w_i &= u^{-1}[c(e_i, \theta_i)] \end{aligned}$$

# Symmetric Information

- The principal's unconstrained maximization problem can then be written as

$$\max_{e_i} x(e_i) - u^{-1}[c(e_i, \theta_i)]$$

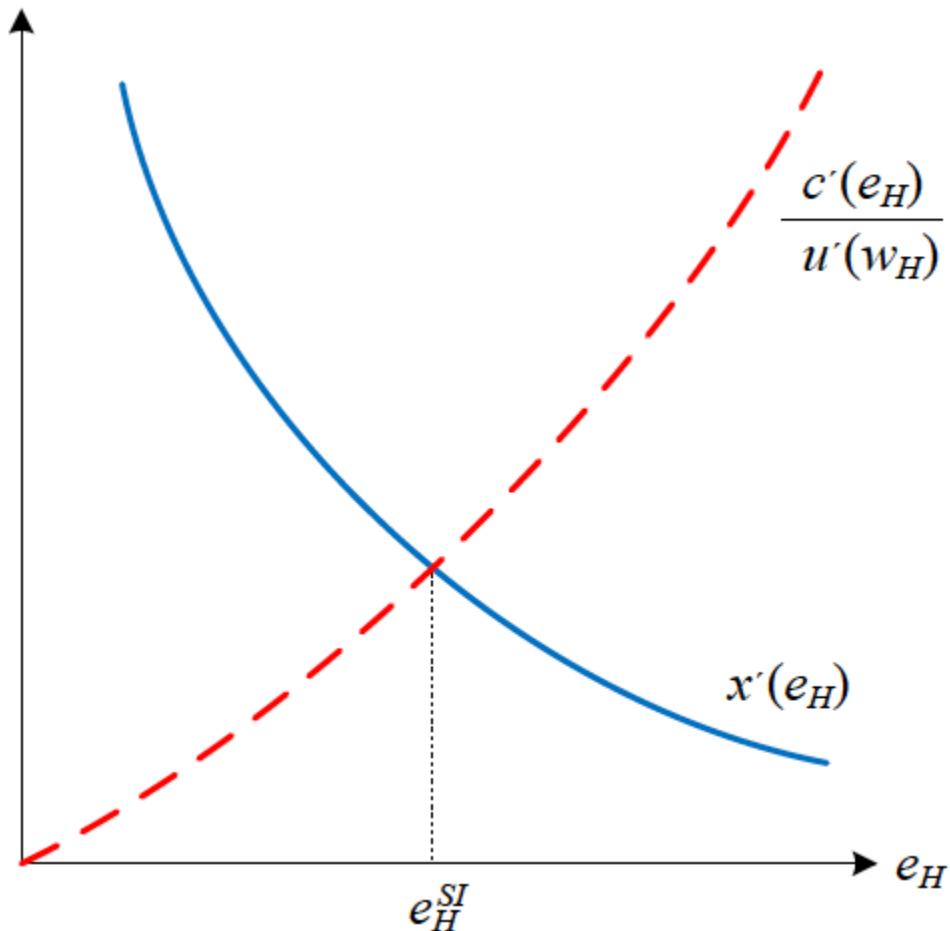
- Taking FOC with respect to  $e_i$  yields

$$x'(e_i) = \frac{1}{u'\{u^{-1}[c(e_i, \theta_i)]\}} c'(e_i, \theta_i)$$

$$x'(e_i) = \frac{c'(e_i, \theta_i)}{u'\{w_i\}}$$

- Hence effort is increased until the point at which the marginal rate of substitution of effort and wage for the firm (left-hand side) coincides with that of the worker (right-hand side).

# Symmetric Information



# Symmetric Information

- Example 6:
  - Consider a principal and an agent of type  $\theta_L = 1$ ,  $\theta_H = 2$ .
  - The probability of facing a low type is  $p = 1/2$ .
  - Productivity of effort is  $x(e) = \log(e)$ , and  $u(w) = w$ .
  - The cost of effort is  $c(e, \theta) = \theta_i e^2$ , with the marginal cost of effort of  $2\theta_i e$ , which is positive and increasing in  $e$ .
  - The principal's profit function is
$$\pi(e, w) = \log(e) - w$$
  - The agent's utility is
$$v(w, e | \theta_i) = w - \theta_i e^2$$

# Symmetric Information

- Taking FOC

$$x'(e_i) = \frac{c'(e_i, \theta_i)}{u'\{w_i\}} \Rightarrow \frac{1}{e_i} = \frac{2\theta_i e_i}{1}$$

- Solving for  $e_i$

$$e_i^2 = \frac{1}{2\theta_i} \rightarrow e_i^{SI} = \left(\frac{1}{2\theta_i}\right)^{1/2}$$

- Use the (PC) constraint,  $u(w_i) = c(e_i, \theta_i)$ , to find optimal salary

$$w_i = \theta_i (e_i^{SI})^2 = \theta_i \left( \left( \frac{1}{2\theta_i} \right)^{1/2} \right)^2 = \frac{1}{2}$$

# Symmetric Information

- Plugging in  $\theta_L = 1$  and  $\theta_H = 2$ , we find optimal contracts

$$(w_H^{SI}, e_H^{SI}) = \left( \frac{1}{2}, \frac{1}{2} \right) = (0.5, 0.5)$$

$$(w_L^{SI}, e_L^{SI}) = \left( \frac{1}{2}, \frac{1}{\sqrt{2}} \right) = (0.5, 0.707)$$

- The firm will pay both types of workers the same wage under symmetric information, but expect a higher effort level from the low-cost worker,  $e_L^{SI} > e_H^{SI}$ .

# Asymmetric Information

- When the firm **cannot** observe the worker's type, it seeks to maximize the expected profits by designing a pair of contracts,  $(w_H, e_H)$  and  $(w_L, e_L)$ , that satisfy four constraints:
  1. voluntary participation of the high-type worker;
  2. voluntary participation of the low-type worker;
  3. the high-type worker prefers the contract  $(w_H, e_H)$  rather than that for the low-type,  $(w_L, e_L)$ ;
  4. the low-type worker prefers the contract  $(w_L, e_L)$  rather than that for the high-type,  $(w_H, e_H)$ .
- Since every type of worker has an incentive to select the contract meant for him, these contracts induce "**self-selection**."

# Asymmetric Information

- The firm solves the following profit maximization problem

$$\max_{w_L, e_L, w_H, e_H} p[x(e_L) - w_L] + (1 - p)[x(e_H) - w_H]$$
$$\text{s.t. } u(w_H) - c(e_H, \theta_H) \geq 0 \quad (\text{PC}_H)$$
$$u(w_L) - c(e_L, \theta_L) \geq 0 \quad (\text{PC}_L)$$
$$u(w_H) - c(e_H, \theta_H) \geq u(w_L) - c(e_L, \theta_H) \quad (\text{IC}_H)$$
$$u(w_L) - c(e_L, \theta_L) \geq u(w_H) - c(e_H, \theta_L) \quad (\text{IC}_L)$$

# Asymmetric Information

- Note that  $(PC_L)$  is implied by  $(IC_L)$  and  $(PC_H)$

$$\begin{aligned} u(w_L) - c(e_L, \theta_L) &\geq u(w_H) - c(e_H, \theta_L) \\ &> u(w_H) - c(e_H, \theta_H) \geq 0 \end{aligned}$$

- The first (weak) inequality stems from  $(IC_L)$ .
- The second (strict) inequality stems from the assumption  $c(e_H, \theta_L) < c(e_H, \theta_H)$ .
- The third (weak) inequality stems from  $(PC_H)$ .

- Hence we obtain  $(PC_L)$

$$u(w_L) - c(e_L, \theta_L) > 0$$

# Asymmetric Information

- The Lagrangian is

$$\begin{aligned}\mathcal{L} = & p[x(e_L) - w_L] + (1 - p)[x(e_H) - w_H] \\ & + \lambda_1[u(w_H) - c(e_H, \theta_H)] \\ & + \lambda_2[u(w_H) - c(e_H, \theta_H) - u(w_L) + c(e_L, \theta_H)] \\ & + \lambda_3[u(w_L) - c(e_L, \theta_L) - u(w_H) + c(e_H, \theta_L)]\end{aligned}$$

# Asymmetric Information

- Taking FOCs

$$\frac{\partial \mathcal{L}}{\partial w_L} = -p - \lambda_2 u'(w_L) + \lambda_3 u'(w_L) = 0$$

$$\frac{\partial \mathcal{L}}{\partial w_H} = -(1-p) + \lambda_1 u'(w_H) + \lambda_2 u'(w_H) - \lambda_3 u'(w_H) = 0$$

$$\frac{\partial \mathcal{L}}{\partial e_L} = px'(e_L) + \lambda_2 c'(e_L, \theta_H) - \lambda_3 c'(e_L, \theta_L) = 0$$

$$\frac{\partial \mathcal{L}}{\partial e_H} = (1-p)x'(e_H) - \lambda_1 c'(e_H, \theta_H) - \lambda_2 c'(e_H, \theta_H) + \lambda_3 c'(e_H, \theta_L) = 0$$

$$\frac{\partial \mathcal{L}}{\partial \lambda_1} = u(w_H) - c(e_H, \theta_H) \geq 0$$

$$\frac{\partial \mathcal{L}}{\partial \lambda_2} = u(w_H) - c(e_H, \theta_H) - u(w_L) + c(e_L, \theta_H) \geq 0$$

$$\frac{\partial \mathcal{L}}{\partial \lambda_3} = u(w_L) - c(e_L, \theta_L) - u(w_H) + c(e_H, \theta_L) \geq 0$$

# Asymmetric Information

- For simplicity, consider that the cost of effort takes the following form

$$c(e, \theta_i) = \theta_i c(e) \text{ for all } i = \{H, L\}$$

where  $c(e)$  is increasing and convex in effort,  $c'(e) \geq 0$  and  $c''(e) \geq 0$ .

- Rearranging the first two FOCs yields

$$-\lambda_2 + \lambda_3 = \frac{p}{u'(w_L)}$$
$$\lambda_1 + \lambda_2 - \lambda_3 = \frac{1-p}{u'(w_H)}$$

- Then adding them together

$$\lambda_1 = \frac{p}{u'(w_L)} + \frac{1-p}{u'(w_H)}$$

# Asymmetric Information

- Hence  $\lambda_1 > 0$ , implying that the constraint associated with Lagrange multiplier  $\lambda_1$ , ( $PC_H$ ), binds:  
$$u(w_H) - c(e_H, \theta_H) = 0$$

# Asymmetric Information

- The third FOC can be written as

$$px'(e_L) = \lambda_3 \theta_L c'(e_L) - \lambda_2 \theta_H c'(e_L)$$

- Rearranging

$$\frac{px'(e_L)}{c'(e_L)} = \lambda_3 \theta_L - \lambda_2 \theta_H$$

- The fourth FOC can be written as

$$(1 - p)x'(e_H) = \lambda_1 \theta_H c'(e_H) - \lambda_3 \theta_L c'(e_H) + \lambda_2 \theta_H c'(e_H)$$

- Rearranging

$$\frac{(1 - p)x'(e_H)}{c'(e_H)} = \lambda_1 \theta_H - (\lambda_3 \theta_L - \lambda_2 \theta_H)$$

# Asymmetric Information

- Combining the two (rearranged) FOCs yields

$$\frac{(1-p)x'(e_H)}{c'(e_H)} = \lambda_1 \theta_H - \frac{px'(e_L)}{c'(e_L)}$$

- Solving for  $\lambda_1 \theta_H$  and using  $\lambda_1 = \frac{p}{u'(w_L)} + \frac{1-p}{u'(w_H)}$  from our results above, we obtain

$$\left[ \frac{p}{u'(w_L)} + \frac{1-p}{u'(w_H)} \right] \theta_H = \frac{px'(e_L)}{c'(e_L)} + \frac{(1-p)x'(e_H)}{c'(e_H)}$$

# Asymmetric Information

- Moreover,  $\lambda_3 > \lambda_2$ , since otherwise the first FOC,  $(\lambda_3 - \lambda_2)u'(w_L) = p$ , could not hold.
- Therefore,  $\lambda_3 > 0$ , which means  $(IC_L)$  binds:  
$$u(w_L) - \theta_L c(e_L) = u(w_H) - \theta_L c(e_H)$$
- Rearranging the right-hand side  
$$\begin{aligned} u(w_L) - \theta_L c(e_L) \\ = u(w_H) - \theta_H c(e_H) + (\theta_H - \theta_L)c(e_H) \end{aligned}$$
- Since  $(PC_H)$ , binds,  $u(w_H) - c(e_H, \theta_H) = 0$ , hence  
$$u(w_L) - \theta_L c(e_L) = (\theta_H - \theta_L)c(e_H)$$

# Asymmetric Information

- Intuition:
  - The most efficient agent,  $\theta_L$ , obtains in equilibrium a positive utility level,  $(\theta_H - \theta_L)c(e_H)$ , that increases in his difference with respect to the least efficient worker,  $\theta_H - \theta_L$ .

# Asymmetric Information

- The incentive compatibility condition of the least efficient worker,  $(IC_H)$ , does not bind, implying that its associated Lagrange multiplier  $\lambda_2 = 0$ .
- Using this result in the first and third FOCs yields

$$\lambda_3 = \frac{p}{u'(w_L)} \text{ and } \frac{px'(e_L)}{c'(e_L)} = \lambda_3 \theta_L$$

- Solving for  $\lambda_3$  and combining the two FOCs

$$\frac{p}{u'(w_L)} = \frac{px'(e_L)}{\theta_L c'(e_L)}$$

- Solving for  $x'(e_L)$

$$x'(e_L) = \frac{\theta_L c'(e_L)}{u'(w_L)}$$

# Asymmetric Information

- Intuition:
  - For the most efficient worker, the equilibrium outcome under asymmetric information **coincides** with the socially optimal result under symmetric information.

# Asymmetric Information

- Using  $\lambda_1 = \frac{p}{u'(w_L)} + \frac{1-p}{u'(w_H)}$ ,  $\lambda_2 = 0$ ,  $\lambda_3 = \frac{p}{u'(w_L)}$  in the fourth FOC, we obtain

$$(1-p)x'(e_H) - \left[ \frac{p}{u'(w_L)} + \frac{1-p}{u'(w_H)} \right] \theta_H c'(e_H) + \left[ \frac{p}{u'(w_L)} \right] \theta_L c'(e_H) = 0$$

- Rearranging

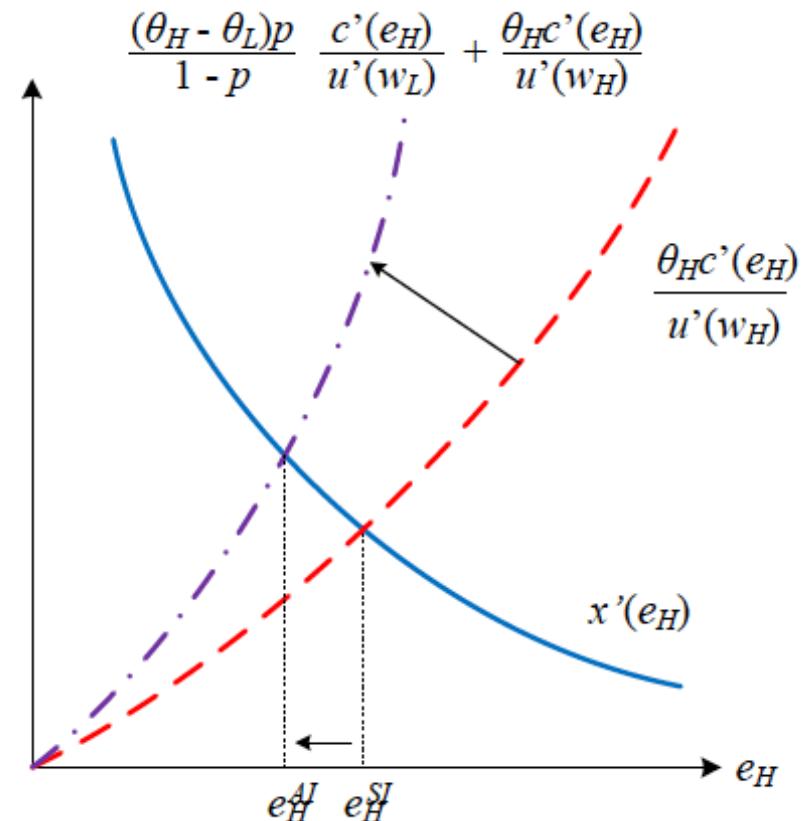
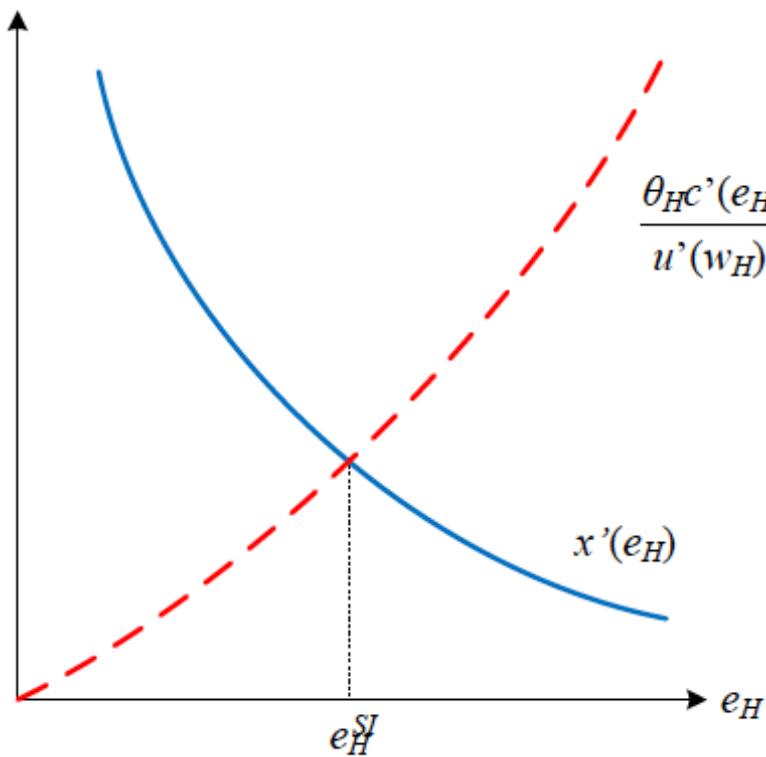
$$\frac{(\theta_H - \theta_L)p}{1-p} \frac{c'(e_H)}{u'(w_L)} + \frac{\theta_H c'(e_H)}{u'(w_H)} = x'(e_H)$$

- The effort level that solves this equation is the **optimal** effort under asymmetric information,  $e_H^{AI}$ .

# Asymmetric Information

- Compare  $e_H^{AI}$  against the effort arising under symmetric information  $e_H^{SI}$ ,  $\frac{\theta_H c'(e_H)}{u'(w_H)} = x'(e_H)$ .
- Given  $\theta_H - \theta_L > 0$ ,  $p > 0$ ,  $c'(e_H) > 0$  and  $u'(w_L) > 0$ ,  
$$\frac{(\theta_H - \theta_L)p}{1 - p} \frac{c'(e_H)}{u'(w_L)} + \frac{\theta_H c'(e_H)}{u'(w_H)} > \frac{\theta_H c'(e_H)}{u'(w_H)}$$
- Hence the effort level under asymmetric information is **lower** than that under symmetric information,  $e_H^{AI} < e_H^{SI}$ .

# Asymmetric Information



# Asymmetric Information

- In summary, the pair of contracts  $(w_H, e_H)$  and  $(w_L, e_L)$  must satisfy the following equations

$$u(w_L) - \theta_L c(e_L) = (\theta_H - \theta_L)c(e_H)$$

$$u(w_H) - c(e_H, \theta_H) = 0$$

$$\frac{\theta_L c'(e_L)}{u'(w_L)} = x'(e_L)$$

$$\frac{(\theta_H - \theta_L)p}{1 - p} \frac{c'(e_H)}{u'(w_L)} + \frac{\theta_H c'(e_H)}{u'(w_H)} = x'(e_H)$$

# Monotonicity in Effort

- Consider that effort levels satisfy  $e_L \geq e_H$ .
  - That is, the worker with the lowest cost of effort exerts a larger effort level than the worker with a high cost of effort.
- Combining  $(IC_L)$  and  $(IC_H)$  to obtain
$$u(w_L) - c(e_L, \theta_L) \geq u(w_H) - c(e_H, \theta_L) > u(w_H) - c(e_H, \theta_H) \geq u(w_L) - c(e_L, \theta_H)$$
  - The first inequality stems from  $(IC_L)$ .
  - The second inequality is due to  $c(e_L, \theta_L) < c(e_H, \theta_H)$ .
  - The third inequality is due to  $(IC_H)$ .
- Hence, the above inequality can be rearranged as
$$c(e_H, \theta_L) - c(e_L, \theta_L) \geq u(w_H) - u(w_L) > c(e_H, \theta_H) - c(e_L, \theta_H)$$

# Monotonicity in Effort

- Multiplying this expression by  $-1$ , and using the first and last terms

$$c(e_L, \theta_L) - c(e_H, \theta_L) < c(e_L, \theta_H) - c(e_H, \theta_H)$$

- This condition indicates that the marginal cost of increasing effort from  $e_H$  to  $e_L$  is higher for the high-type than for the low-type worker.
- Evaluating this condition in the cost of effort function  $c(e, \theta) = \theta c(e)$

$$\theta_L [c(e_L) - c(e_H)] < \theta_H [c(e_L) - c(e_H)]$$

- Since  $\theta_L < \theta_H$ , we must have  $c(e_L) > c(e_H)$ .
- Hence effort is larger for the worker with the low cost of effort,  $e_L > e_H$

# Monotonicity in Effort

- **Example 7:**
  - Let us use Example 6 to calculate the optimal contracts under asymmetric information.
  - Taking FOCs from above

$$u(w_L) - \theta_L c(e_L) = (\theta_H - \theta_L)c(e_H) \Rightarrow w_L - e_L^2 = e_H^2$$

$$u(w_H) - \theta_H c(e_H) = 0 \Rightarrow w_H = 2e_H^2$$

$$x'(e_L) = \frac{\theta_L c'(e_L)}{u'(w_L)} \Rightarrow \frac{1}{e_L} = \frac{2e_L}{1} \rightarrow 2e_L^2 = 1 \rightarrow e_L = \frac{1}{\sqrt{2}}$$

$$\frac{(\theta_H - \theta_L)p}{1-p} \frac{c'(e_H)}{u'(w_L)} + \frac{\theta_H c'(e_H)}{u'(w_H)} = x'(e_H) \Rightarrow \frac{2e_H}{1} + \frac{4e_H}{1}$$
$$= \frac{1}{e_H} \rightarrow e_H = \frac{1}{\sqrt{6}}$$

# Monotonicity in Effort

- Example 7: (con't)
  - From the last two FOCs, we obtain the equilibrium effort levels  $e_L = \frac{1}{\sqrt{2}}$  and  $e_H = \frac{1}{\sqrt{6}}$ .
  - From the first equation

$$w_L - \frac{1}{2} = \frac{1}{6} \rightarrow w_L = \frac{2}{3}$$

- From the second equation

$$w_H = 2 \cdot \frac{1}{6} \rightarrow w_H = \frac{1}{3}$$

- Therefore, the optimal pair of contracts is

$$(w_H^{AI}, e_H^{AI}) = \left( \frac{1}{3}, \frac{1}{\sqrt{6}} \right) = (0.333, 0.408)$$

$$(w_L^{AI}, e_L^{AI}) = \left( \frac{2}{3}, \frac{1}{\sqrt{2}} \right) = (0.667, 0.707)$$

# Monotonicity in Effort

- Example 7: (con't)
  - The introduction of asymmetric information entails:
    - *No changes* in effort for the low-cost worker relative to symmetric information
$$e_L^{AI} = e_L^{SI} = 0.707$$
    - *Lower* effort for the high-cost worker than under symmetric information
$$e_H^{AI} = 0.408 < 0.5 = e_H^{SI}$$
    - *Higher* salaries for the low-cost worker than under symmetric information
$$w_L^{AI} = 0.667 > 0.5 = w_L^{SI}$$
    - *Lower* salaries for the high-cost worker
$$w_H^{AI} = 0.333 < 0.5 = w_H^{SI}$$

# Monotonicity in Effort

- **Example 7:** (con't)
  - The net utility that each type of worker obtains under asymmetric information is
$$u_H^{AI} = w_H - 2e_H^2 = 0$$
$$u_L^{AI} = w_L - e_L^2 = 0.167$$
  - Hence the worker with a low cost of effort captures an information rent
$$u_L^{AI} - u_L^{SI} = 0.167 - 0 = 0.167$$
  - The worker with a high cost of effort does not
$$u_H^{AI} = u_H^{SI} = 0$$
  - Intuitively, the firm must compensate the low-cost worker above symmetric information terms in order for him to reveal his type.

# Application of Adverse Selection—Regulation

# Regulation

- Regulatory agencies often cannot observe some characteristics of the regulated firm or of individual.
- Examples:
  - A firm's production costs
  - A firm's costs from pollution abatement
  - A consumer's willingness to pay for certain products
- In these scenarios the privately informed party (e.g., firm) has incentives to overstate its costs.
- Hence the regulator cannot directly ask firms about their production costs since responses would be unreliable.
- Adverse selection models offer an alternative contracting tool to extract information from privately informed firms (or consumers).

# Regulation

- Consider that a government regulating a monopoly with cost function

$$c(q) = C + cq$$

where  $C$  is fixed costs and  $c > 0$  is marginal costs.

- The consumer pays  $F$  for the bulk of  $q$  units consumed, and the monopolist may receive a lump-sum subsidy from the government of  $S$ .
- Assume that the shadow cost of raising public funds is  $g \in (0,1)$ , thus implying that the total cost of providing a subsidy  $S$  to the monopolist is  $(1 + g)S$ .
- Analyze settings where government has symmetric and asymmetric information about the monopolist's costs.

# Regulation- Symmetric Information

- Consider that the government can **perfectly** observe the monopolist's marginal cost of production  $c$ .
- The government solves the following problem subject to PCs of both the monopolist and the consumer:

$$\begin{aligned} \max_{F,S,q} \quad & [u(q) - F] + [F + S - C - cq] - (1 + g)S \\ \text{s.t.} \quad & F + S - C - cq \geq 0 \quad (\text{PC}_{\text{Monop}}) \\ & u(q) - F \geq 0 \quad (\text{PC}_{\text{Consum}}) \end{aligned}$$

where  $u(q) - F$  is the consumer's utility after paying  $F$  for  $q$  units; and  $F + S - C - cq$  is the monopolist's profits.

- The Lagrangian is

$$\begin{aligned} \mathcal{L} = & [u(q) - F] + [F + S - C - cq] - (1 + g)S \\ & + \lambda_1[F + S - C - cq] + \lambda_2[u(q) - F] \end{aligned}$$

# Regulation- Symmetric Information

- Taking FOCs yields

$$\frac{\partial \mathcal{L}}{\partial F} = \lambda_1 - \lambda_2 = 0 \rightarrow \lambda_1 = \lambda_2$$

$$\frac{\partial \mathcal{L}}{\partial S} = 1 - (1 + g) + \lambda_1 = 0 \rightarrow \lambda_1 = g$$

$$\frac{\partial \mathcal{L}}{\partial q} = u'(q) - c - \lambda_1 c + \lambda_2 u'(q) = 0$$

$$\lambda_1 [F + S - C - cq] = 0$$

$$\lambda_2 [u(q) - F] = 0$$

- Combining the first and second FOC

$$\lambda_1 = \lambda_2 = g$$

# Regulation- Symmetric Information

- Plugging this result into the third FOC yields

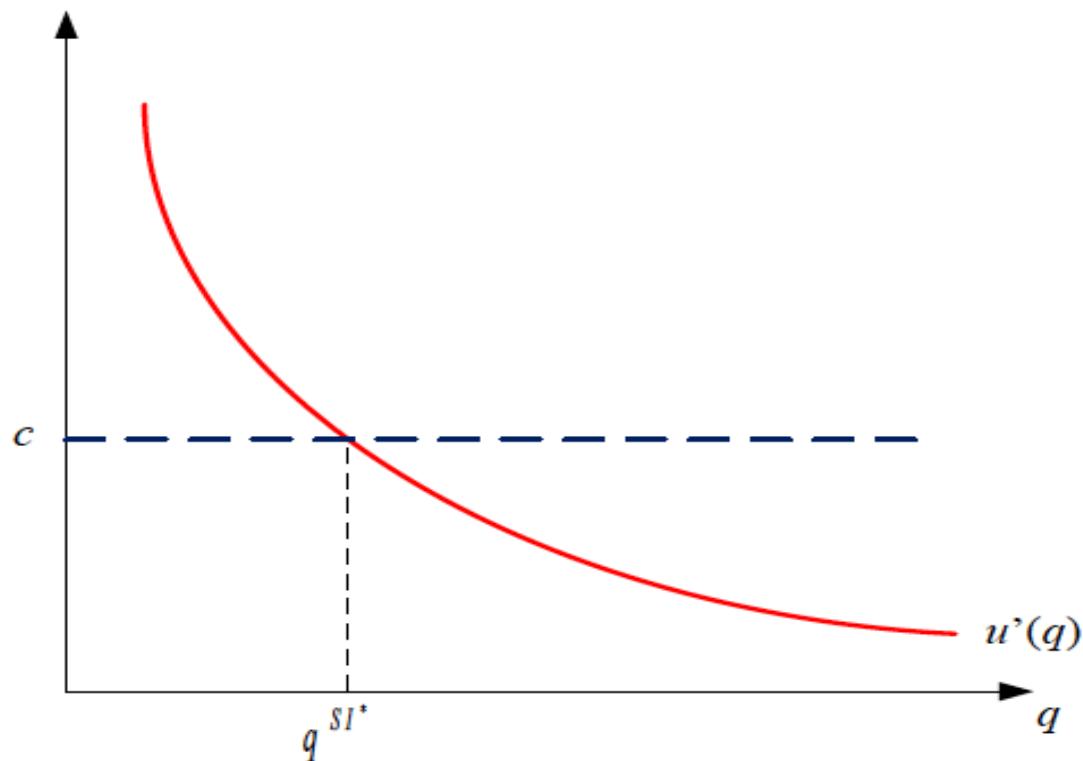
$$u'(q) - c - gc + gu'(q) = 0$$

- Rearranging

$$(1 + g)u'(q) = (1 + g)c \Leftrightarrow u'(q) = c$$

- That is,  $q$  is increased until the point where marginal utility from further units coincides with its marginal cost.
- Hence, under symmetric information, the monopolist's production is **efficient**.

# Regulation- Symmetric Information



# Regulation- Asymmetric Information

- Consider now that the government **cannot** observe the monopolist's marginal cost of production  $c$ .
- Marginal cost can be low or high  $c = \{c_L, c_H\}$ , where  $c_L < c_H$ , with associated probabilities  $p$  and  $1 - p$ , respectively.
- The government offers two menus  $(F_L, S_L, q_L)$  and  $(F_H, S_H, q_H)$  to maximize the expected social welfare subject to PCs of both the monopolist and the consumer.

# Regulation- Asymmetric Information

- The government's maximization problem is

$$\max_{(F_L, S_L, q_L), (F_H, S_H, q_H)} p[u(q_L) - F_L + F_L + S_L - C - c_L q_L - (1 + g)S_L] + (1 - p)[u(q_H) - F_H + F_H + S_H - C - c_H q_H - (1 + g)S_H]$$

s.t.

$$F_L + S_L - C - c_L q_L \geq 0 \quad (\text{PC}_{\text{Monop,L}})$$
$$F_H + S_H - C - c_H q_H \geq 0 \quad (\text{PC}_{\text{Monop,H}})$$
$$F_L + S_L - C - c_L q_L \geq F_H + S_H - C - c_L q_H \quad (\text{IC}_{\text{Monop,L}})$$
$$F_H + S_H - C - c_H q_H \geq F_L + S_L - C - c_H q_L \quad (\text{IC}_{\text{Monop,H}})$$
$$u(q_L) - F_L \geq 0 \quad (\text{PC}_{\text{Consum,L}})$$
$$u(q_H) - F_H \geq 0 \quad (\text{PC}_{\text{Consum,H}})$$

# Regulation- Asymmetric Information

- Timeframe:
  - The government offers contracts
  - The monopolist chooses one of contracts, and then the  $K$ -type monopolist offers  $q_K$  units to the consumer at a lump-sum price of  $F_K$  where  $K = \{L, H\}$ .
  - The consumer can accept or reject the offer.
- *Practice:* Solve the problem on your own.
  - Output of the low type coincides with that under symmetric information, whereas, that of the high type is smaller.
  - However, the subsidy that the high-cost firm receives is lower than under symmetric information, while that of the low-cost firm is the same.

# Regulation- Asymmetric Information

- Example 8:
  - Consider consumers with utility function  $u(q) = \sqrt{q}$ , a monopoly with cost function  $c(q) = \frac{1}{q} + cq$ , where marginal costs can be high  $c_H = \frac{1}{8}$  or low  $c_L = \frac{1}{16}$ , with probability  $p = \frac{1}{2}$ .
  - The shadow cost of raising public funds is  $g = \frac{1}{24}$ .
  - Symmetric information entails an output level that solves
$$\frac{1}{2\sqrt{q}} = c_K$$
which yields  $q_H^{SI} = 16$  and  $q_L^{SI} = 64$ .
  - Asymmetric information entails output levels
$$q_L^{AI} = q_L^{SI} = 64$$
$$q_H^{AI} \cong 15.38 < q_H^{SI} = 16$$